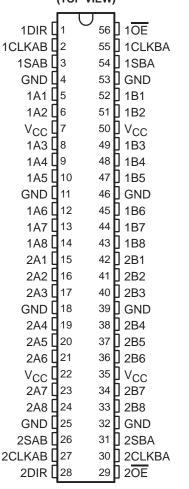
- Members of the Texas Instruments Widebus™ Family
- State-of-the-Art Advanced BiCMOS Technology (ABT) Design for 3.3-V Operation and Low Static-Power Dissipation
- Support Mixed-Mode Signal Operation (5-V Input and Output Voltages With 3.3-V V_{CC})
- Support Unregulated Battery Operation Down to 2.7 V
- Typical V_{OLP} (Output Ground Bounce)
 < 0.8 V at V_{CC} = 3.3 V, T_A = 25°C
- I_{off} and Power-Up 3-State Support Hot Insertion
- Bus Hold on Data Inputs Eliminates the Need for External Pullup/Pulldown Resistors
- Distributed V_{CC} and GND Pin Configuration Minimizes High-Speed Switching Noise
- Flow-Through Architecture Optimizes PCB Layout
- Latch-Up Performance Exceeds 500 mA Per JESD 17
- ESD Protection Exceeds 2000 V Per MIL-STD-883, Method 3015; Exceeds 200 V Using Machine Model (C = 200 pF, R = 0)
- Package Options Include Plastic Shrink Small-Outline (DL) and Thin Shrink Small-Outline (DGG) Packages and 380-mil Fine-Pitch Ceramic Flat (WD) Package Using 25-mil Center-to-Center Spacings

SN54LVTH16646 . . . WD PACKAGE SN74LVTH16646 . . . DGG OR DL PACKAGE (TOP VIEW)



description

The 'LVTH16646 devices are 16-bit bus transceivers designed for low-voltage (3.3-V) V_{CC} operation, but with the capability to provide a TTL interface to a 5-V system environment.

These devices can be used as two 8-bit transceivers or one 16-bit transceiver. Data on the A or B bus is clocked into the registers on the low-to-high transition of the appropriate clock (CLKAB or CLKBA) input. Figure 1 illustrates the four fundamental bus-management functions that can be performed with the 'LVTH16646 devices.



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description (continued)

Output-enable (\overline{OE}) and direction-control (DIR) inputs are provided to control the transceiver functions. In the transceiver mode, data present at the high-impedance port may be stored in either register or in both. The select-control (SAB and SBA) inputs can multiplex stored and real-time (transparent mode) data. The circuitry used for select control eliminates the typical decoding glitch that occurs in a multiplexer during the transition between stored and real-time data. DIR determines which bus receives data when \overline{OE} is low. In the isolation mode (\overline{OE} high), A data can be stored in one register and/or B data can be stored in the other register.

When an output function is disabled, the input function is still enabled and can be used to store and transmit data. Only one of the two buses, A or B, can be driven at a time.

Active bus-hold circuitry is provided to hold unused or floating data inputs at a valid logic level.

When V_{CC} is between 0 and 1.5 V, the devices are in the high-impedance state during power up or power down. However, to ensure the high-impedance state above 1.5 V, \overline{OE} should be tied to V_{CC} through a pullup resistor; the minimum value of the resistor is determined by the current-sinking capability of the driver.

These devices are fully specified for hot-insertion applications using I_{off} and power-up 3-state. The I_{off} circuitry disables the outputs, preventing damaging current backflow through the devices when they are powered down. The power-up 3-state circuitry places the outputs in the high-impedance state during power up and power down, which prevents driver conflict.

The SN54LVTH16646 is characterized for operation over the full military temperature range of –55°C to 125°C. The SN74LVTH16646 is characterized for operation from –40°C to 85°C.

FUNCTION TABLE

INPUTS						DAT	A I/O	OPERATION OR FUNCTION		
ŌĒ	DIR	CLKAB	CLKBA	SAB	SBA	A1-A8	B1-B8	OPERATION OR FUNCTION		
Х	Х	1	Х	Х	Х	Input Unspecified [†]		Store A, B unspecified [†]		
Х	Χ	Χ	\uparrow	X	Χ	Unspecified [†]	Input	Store B, A unspecified [†]		
Н	Х	1	↑	Х	Х	Input	Input	Store A and B data		
Н	X	H or L	H or L	X	Χ	Input disabled	Input disabled	Isolation, hold storage		
L	L	Х	Х	Х	L	Output	Input	Real-time B data to A bus		
L	L	Χ	H or L	X	Н	Output	Input	Stored B data to A bus		
L	Н	Х	Х	L	Х	Input	Output	Real-time A data to B Bus		
L	Н	H or L	Χ	Н	X	Input	Output	Stored A data to bus		

[†] The data-output functions may be enabled or disabled by various signals at $\overline{\text{OE}}$ or DIR. Data-input functions always are enabled, i.e., data at the bus terminals is stored on every low-to-high transition of the clock inputs.



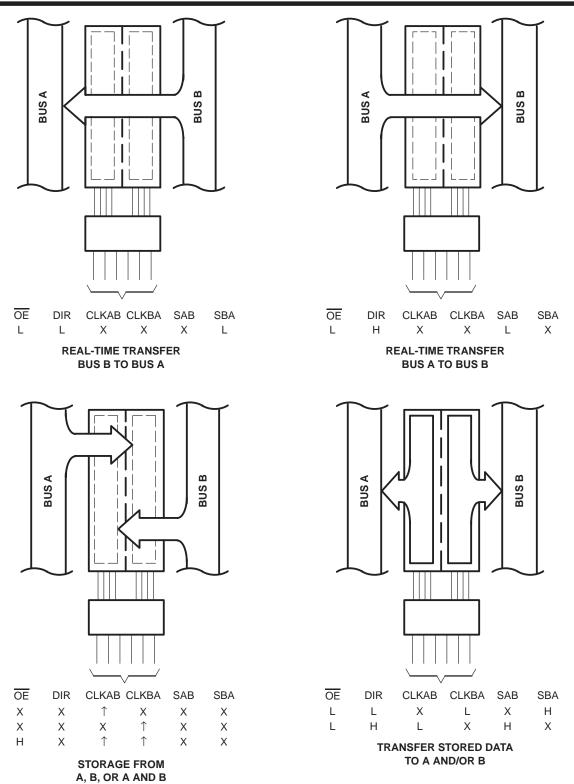
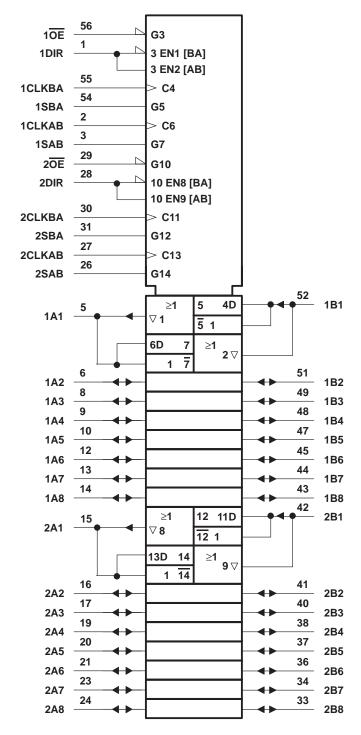


Figure 1. Bus-Management Functions



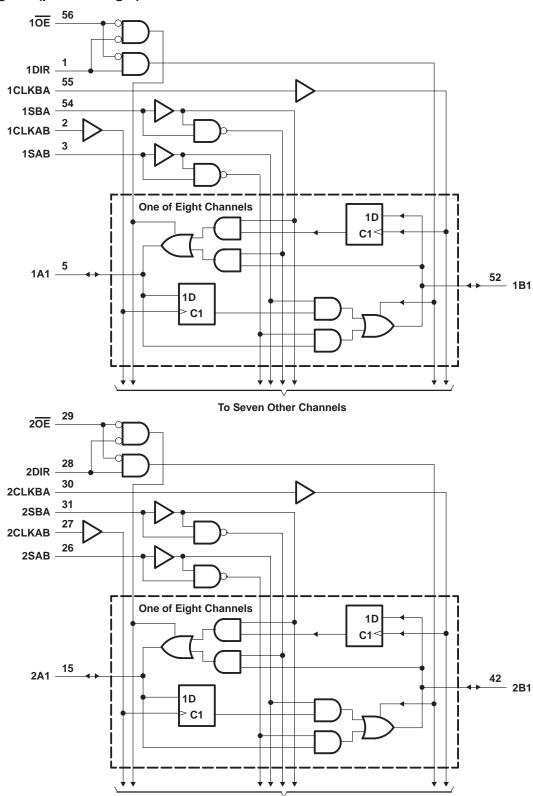
logic symbol†



[†] This symbol is in accordance with ANSI/IEEE Std 91-1984 and IEC Publication 617-12.



logic diagram (positive logic)





To Seven Other Channels

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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Supply voltage range, V _{CC}		
Input voltage range, V _I (see Note 1)		–0.5 V to 7 V
Voltage range applied to any output in the high	gh-impedance	
or power-off state, VO (see Note 1)		–0.5 V to 7 V
Voltage range applied to any output in the high	gh state, V _O (see Note 1)	0.5 V to V _{CC} + 0.5 V
Current into any output in the low state, Io: \$	SN54LVTH16646	96 mA
	SN74LVTH16646	
Current into any output in the high state, IO	see Note 2): SN54LVTH16646	48 mA
	SN74LVTH16646	64 mA
Input clamp current, I _{IK} (V _I < 0)		
Output clamp current, I _{OK} (V _O < 0)		
Package thermal impedance, θ _{JA} (see Note	3): DGG package	
, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		
Storage temperature range, T _{stq}		–65°C to 150°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

- NOTES: 1. The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.
 - 2. This current flows only when the output is in the high state and $V_O > V_{CC}$.
 - 3. The package thermal impedance is calculated in accordance with JESD 51.

recommended operating conditions (see Note 4)

		SN54LVTI	116646	SN74LVTI	H16646	UNIT	
			MIN	MAX	MIN	MAX	UNIT
VCC	Supply voltage	2.7	3.6	2.7	3.6	V	
VIH	High-level input voltage		2	3	2		V
V _{IL}	Low-level input voltage		0.8		8.0	V	
VI	Input voltage	4	5.5		5.5	V	
loн	High-level output current		7	-24		-32	mA
loL	Low-level output current		2	48		64	mA
Δt/Δν	Input transition rise or fall rate	Outputs enabled	0,0	10		10	ns/V
Δt/ΔV _{CC}	Power-up ramp rate		200	·	200		μs/V
T _A	Operating free-air temperature		-55	125	-40	85	°C

NOTE 4: All unused control inputs of the device must be held at V_{CC} or GND to ensure proper device operation. Refer to the TI application report, Implications of Slow or Floating CMOS Inputs, literature number SCBA004.



electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST OF	ONDITIONS	SN5	4LVTH16	6646	SN7	LINUT				
PAR	RAMETER	1531 (4	ONDITIONS	MIN	TYP†	MAX	MIN	TYP†	MAX	UNIT		
VIK		$V_{CC} = 2.7 \text{ V},$	I _I = -18 mA			-1.2			-1.2	V		
		$V_{CC} = 2.7 \text{ V to } 3.6 \text{ V},$	$I_{OH} = -100 \mu A$	V _{CC} -0	.2		V _{CC} -0	.2				
V		$V_{CC} = 2.7 \text{ V},$	I _{OH} = -8 mA	2.4			2.4			\ _\		
VOH		V _{CC} = 3 V	I _{OH} = -24 mA	2						V		
		VCC = 3 V	$I_{OH} = -32 \text{ mA}$				2					
		V _{CC} = 2.7 V	I _{OL} = 100 μA			0.2			0.2			
		VCC = 2.7 V	I _{OL} = 24 mA			0.5			0.5			
Vol			I _{OL} = 16 mA			0.4			0.4	V		
VOL		V _{CC} = 3 V	$I_{OL} = 32 \text{ mA}$			0.5			0.5	V		
		\(\(\text{CC} = 3\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	$I_{OL} = 48 \text{ mA}$			0.55						
			I _{OL} = 64 mA			2			0.55			
	Control inputs	$V_{CC} = 3.6 \text{ V},$	$V_I = V_{CC}$ or GND		Š	±1			±1			
	Control inputs	$V_{CC} = 0 \text{ or } 3.6 \text{ V},$	V _I = 5.5 V		200	10			10			
lį	A or B ports‡	V _{CC} = 3.6 V	V _I = 5.5 V 20						20	μΑ		
			VI = VCC		2	1			1			
			V _I = 0	- 5				-5				
l _{off}		$V_{CC} = 0$,	V_I or $V_O = 0$ to 4.5 V	Q					±100	μΑ		
	A or B ports	V _{CC} = 3 V	V _I = 0.8 V	75			75					
I _{I(hold)}		VCC = 3 V	V _I = 2 V	-75	-75			- 75				
		V _{CC} = 3.6 V§,	$V_{ } = 0 \text{ to } 3.6 \text{ V}$						±500			
I _{OZPU}		$\frac{V_{CC}}{OE} = 0$ to 1.5 V, $V_{O} = 0$	0.5 V to 3 V,			±100*			±100	μΑ		
I _{OZPD}		$\frac{\text{V}_{\text{CC}}}{\text{OE}}$ = 1.5 V to 0, V _O = 0.5 V to 3 V, $\frac{\text{OE}}{\text{OE}}$ = don't care				±100*			±100	μΑ		
lcc			Outputs high			0.19			0.19			
		$V_{CC} = 3.6 \text{ V}, I_{O} = 0,$ $V_{I} = V_{CC} \text{ or GND}$	Outputs low			5			5	mA		
		1 - 100 31 3145	Outputs disabled			0.19			0.19			
ΔI _{CC} ¶		$V_{CC} = 3 \text{ V to } 3.6 \text{ V}$, One input at $V_{CC} - 0.6 \text{ V}$, Other inputs at V_{CC} or GND				0.2			0.2	mA		
Ci		V _I = 3 V or 0			4			4		pF		
C _{io}		V _O = 3 V or 0			10			10		pF		

^{*} On products compliant to MIL-PRF-38535, this parameter is not production tested. † All typical values are at $V_{CC}=3.3$ V, $T_{A}=25^{\circ}C$. ‡ Unused pins at V_{CC} or GND

[§] This is the bus-hold maximum dynamic current. It is the minimum overdrive current required to switch the input from one state to another.

This is the increase in supply current for each input that is at the specified TTL voltage level rather than V_{CC} or GND.

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timing requirements over recommended operating free-air temperature range (unless otherwise noted) (see Figure 2)

				SN54LVTH16646				SN74LVTH16646			
				$V_{CC} = 3.3 \text{ V} \pm 0.3 \text{ V} $ $V_{CC} = 2.7$		2.7 V	7 V $V_{CC} = 3.3 \text{ V} \\ \pm 0.3 \text{ V}$		V _{CC} = 2.7 V		UNIT
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
fclock	Clock frequency			150		150		150		150	MHz
t _W	Pulse duration, CLK high or low		3.3		3.3		3.3		3.3		ns
t _{su}	Setup time, A or B before CLKAB↑ or CLKBA↑	Data high	1.2	o c	1.5		1.2		1.5		ns
		Data low	2	o Pool	2.8		2		2.8		115
^t h	Hold time,	Data high	0.5	.6,,	0		0.5		0		
	A or B after CLKAB↑ or CLKBA↑ Data low		0.5		0.5		0.5		0.5		ns

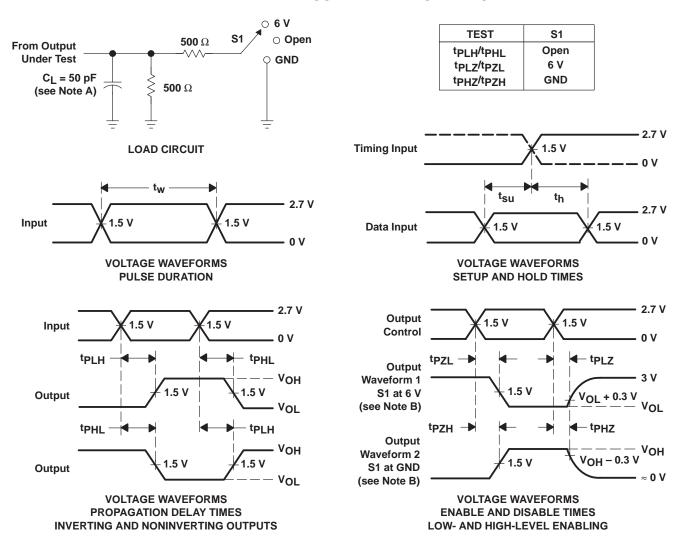
switching characteristics over recommended operating free-air temperature range, $C_L = 50$ pF (unless otherwise noted) (see Figure 2)

		TO (OUTPUT)	5	SN54LV	ГН16646			UNIT					
PARAMETER	FROM (INPUT)		V _{CC} = 3.3 V ± 0.3 V		V _{CC} = 2.7 V		V _{CC} = 3.3 \ ± 0.3 V		V	V _{CC} = 2.7 V			
			MIN	MAX	MIN	MAX	MIN	TYP [†]	MAX	MIN	MAX		
f _{max}			150		150		150			150		MHz	
t _{PLH}	CLKBA or CLKAB	A or B	1.3	4.5		5	1.3	2.8	4.2		4.7	ns	
^t PHL		AOIB	1.3	4.5		5	1.3	2.8	4.2		4.7	115	
t _{PLH}	A or B	A or B	B or A	1	3.6		4.1	1	2.4	3.4		3.9	ns
^t PHL		BOIA	1	3.6	N ₂	4.1	1	2.1	3.4		3.9	115	
t _{PLH}	SBA or SAB‡	A or B	1	4.7	1/4	5.6	1	2.8	4.5		5.4	ns	
^t PHL	SBA OI SAB+	AOIB	1	4.7	74. O	5.6	1	3	4.5		5.4	113	
^t PZH	ŌĒ	A or B	1	4.5		5.4	1	2.5	4.3		5.2	ns	
t _{PZL}	OE	AOIB	1	4.5		5.4	1	2.6	4.3		5.2	115	
^t PHZ	ŌE	A or B	2	5.8		6.3	2	4	5.6		6.1	ns	
tPLZ] 06	AOIB	2	5.6		6.3	2	3.6	5.4		6.1	115	
^t PZH	DIR	A or B	1	4.6		5.5	1	3	4.4		5.3	ns	
tPZL	DIK	AUIB	1	4.6		5.5	1	3	4.4		5.3	115	
^t PHZ	DIR	A or B	1.5	6		7.1	1.5	3.9	5.7		6.8	ns	
tPLZ	DIK	AUB	1.5	5.5		6	1.5	3.6	5.2		5.7	115	

[†] All typical values are at $V_{CC} = 3.3 \text{ V}$, $T_A = 25^{\circ}\text{C}$.

[‡] These parameters are measured with the internal output state of the storage register opposite that of the bus input.

PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L includes probe and jig capacitance.

- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz, $Z_O = 50 \ \Omega$, $t_f \leq 2.5 \ ns$, $t_f \leq 2.5 \ ns$.
- D. The outputs are measured one at a time with one transition per measurement.

Figure 2. Load Circuit and Voltage Waveforms

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