## Preliminary Technical Data

## FEATURES

## Single-ended-to-differential converter

Ultralow distortion
120 dBc THD @ 10 kHz

## Low noise

97 dB SNR @ $100 \mathrm{kHz}, \mathrm{V}_{\mathrm{o}}=4 \mathrm{~V}$ p-p
Extremely low power
2.1 mA (3 V supply)

High input impedance
Easy-to-use gain adjustment
No external components for $\mathbf{G}=+2$
External resistors can be used for additional gain
High speed
$32 \mathrm{MHz},-3 \mathrm{~dB}$ bandwidth ( $\mathbf{G}=+2$ )
Fast settling time
Rail-to-rail output
Disable
Wide supply voltage range: 2.7 V to 12 V


## APPLICATIONS

Single supply data acquisition systems
Instrumentation
Process control
Battery-power systems
Medical instruments

## GENERAL DESCRIPTION

The ADA4941-1 is a low power, differential driver for 16 - to 18 bit ADCs. Configured in an easy-to-use, single-ended-todifferential $G=+2$ configuration, the ADA4941-1 requires no external components to drive ADCs with differential inputs provided that the IN- pin is tied to the OUT+ pin. A resistive network around the IN- pin can be used for additional gain as needed. The ADA4941-1 provides essential benefits, such as low distortion and high SNR, that are required for driving high resolution ADCs.

With a wide input voltage range ( 0 V to 4 V on a single 5 V supply), rail-to-rail output, and high input impedance, the ADA4941-1 is designed to drive single-supply ADCs found in a variety of low power applications, including battery-operated instruments and single-supply data acquisition systems.

FUNCTIONAL BLOCK DIAGRAM


Figure 1.

The ADA4941-1 is manufactured on ADI's proprietary $2^{\text {nd }}$ generation XFCB process that enables the single-ended-todifferential converter to achieve 18-bit performance using only 2.1 mA of supply current.

The ADA4941-1 is ideal for driving 16- to 18-bit differential PulSAR ${ }^{m i}$ ADCs such as the AD7690 and AD7691.

The ADA4941-1 is available in a small 8 lead LFCSP packaging as well as 8 -lead SOIC packaging. The ADA4941-1 is rated to work over the extended industrial temperature range, $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$.

## Rev. PrA

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## SPECIFICATIONS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}=3 \mathrm{~V}$, unless otherwise noted.
Table 1.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DYNAMIC PERFORMANCE -3 dB Bandwidth <br> Overdrive Recovery Time Slew Rate Settling Time 0.0004\% | $\begin{aligned} & \mathrm{V}_{\mathrm{o}}=0.1 \mathrm{~V} \text { p-p } \\ & \mathrm{V}_{\mathrm{o}}=2.0 \mathrm{~V} \text { p-p } \\ & \mathrm{V}_{\mathrm{o}}=2 \mathrm{~V} \text { step } \\ & \mathrm{V}_{\mathrm{o}}=2 \mathrm{~V} \text { p-p step } \end{aligned}$ |  | $\begin{aligned} & 30 \\ & 6.6 \\ & 300 \\ & 22.5 \\ & 0.3 \end{aligned}$ |  | MHz <br> MHz <br> ns <br> $\mathrm{V} / \mu \mathrm{s}$ <br> $\mu \mathrm{s}$ |
| NOISE/DISTORTION PERFORMANCE <br> THD <br> SNR <br> RTO Voltage Noise Input Current Noise | $\begin{aligned} & \mathrm{f}_{\mathrm{c}}=10 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{~V} p-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=1 \mathrm{MHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{Vp}-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=100 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{Vp}-\mathrm{p} \\ & \mathrm{f}=100 \mathrm{kHz} \\ & \mathrm{f}=100 \mathrm{kHz} \end{aligned}$ |  | $\begin{aligned} & 105 \\ & 57 \\ & 91 \\ & 1 \end{aligned}$ |  | dBc <br> dBc <br> dB <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> $\mathrm{pA} / \sqrt{ } \mathrm{Hz}$ |
| DC PERFORMANCE <br> Differential Input Offset Voltage <br> Differential Input Offset Voltage Drift <br> Common-Mode Offset Voltage <br> Common-Mode Offset Voltage Drift <br> Input Bias Current <br> Input Offset Current <br> Gain <br> Gain Error <br> Gain Error Drift | IN and REF <br> IN and REF (+OUT - -OUT)/(IN - REF) |  | $\begin{aligned} & 0.2 \\ & \\ & 2.2 \\ & 0.2 \\ & 2 \\ & 0.1 \\ & 0.01 \end{aligned}$ | . 5 | mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> $\mu \mathrm{A}$ <br> $\mu \mathrm{A}$ <br> V/V <br> \% <br> $\% /{ }^{\circ} \mathrm{C}$ |
| INPUT CHARACTERISTICS <br> Input Resistance <br> Input Capacitance <br> Input Common-Mode Voltage Range <br> Common-Mode Rejection Ratio | IN and REF IN and REF $V_{\text {cм }}= \pm 2.5 \mathrm{~V}$ | 0.1 | $\begin{aligned} & 12 \\ & 2 \\ & 110 \end{aligned}$ | 2 | $\mathrm{M} \Omega$ <br> pF <br> V <br> dB |
| OUTPUT CHARACTERISTICS <br> Output Voltage Swing: VON VOP <br> Output Current Capacitive Load Drive | $\begin{aligned} & R_{L}=1 \mathrm{k} \Omega \\ & R_{L}=1 \mathrm{k} \Omega \end{aligned}$ |  | $\begin{aligned} & 0.1 \text { to } 2.9 \\ & 0.1 \text { to } 2.9 \\ & 25 \end{aligned}$ |  | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~mA} \\ & \mathrm{pF} \end{aligned}$ |
| POWER SUPPLY <br> Operating Range <br> Quiescent Current <br> Quiescent Current—Disable <br> Power Supply Rejection Ration $\begin{aligned} & + \text { +PSRR } \\ & \text {-PSRR } \end{aligned}$ |  | 2.7 | 2.1 <br> 30 <br> 110 <br> 110 | 12 | V mA $\mu \mathrm{A}$ dB dB |
| DISABLE <br> $V_{\text {DIS }} H i g h$ <br> Vis Low <br> Input Current $\mathrm{V}_{\mathrm{DIS}}=\mathrm{HIGH} / \mathrm{LOW}$ <br> Turn-On Time <br> Turn-Off Time |  |  | $\begin{aligned} & 1.8 \\ & 1.6 \\ & 5 / 10 \\ & 30 \\ & 0.65 \end{aligned}$ |  | $\begin{aligned} & V \\ & V \\ & \mu \mathrm{~A} \\ & \mu \mathrm{~s} \\ & \mu \mathrm{~s} \end{aligned}$ |

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{S}}=5 \mathrm{~V}$, unless otherwise noted.
Table 2.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DYNAMIC PERFORMANCE -3 dB Bandwidth <br> Overdrive Recovery Time Slew Rate Settling Time 0.0004\% | $\begin{aligned} & \mathrm{V}_{\mathrm{o}}=0.1 \mathrm{Vp}-\mathrm{p} \\ & \mathrm{~V}_{\mathrm{o}}=2.0 \mathrm{Vp}-\mathrm{p} \end{aligned}$ <br> 0 V to 5 V step overdrive <br> $\mathrm{V}_{\mathrm{o}}=2 \mathrm{~V}$ step <br> $\mathrm{V}_{\mathrm{o}}=6 \mathrm{~V}$ p-p step |  | $\begin{aligned} & 31 \\ & 7.0 \\ & 350 \\ & 25 \\ & 610 \end{aligned}$ |  | MHz <br> MHz <br> ns <br> V/ $\mu \mathrm{s}$ <br> ns |
| NOISE/DISTORTION PERFORMANCE THD <br> SNR <br> RTO Voltage Noise Input Current Noise | $\begin{aligned} & \mathrm{f}_{\mathrm{c}}=10 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=1 \mathrm{MHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=100 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=4 \mathrm{Vp}-\mathrm{p}, \mathrm{fb}=2 \mathrm{MHz} \\ & \mathrm{f}=100 \mathrm{kHz} \\ & \mathrm{f}=100 \mathrm{kHz} \end{aligned}$ |  | $\begin{aligned} & 120 \\ & 72 \\ & 97 \end{aligned}$ |  | dBc <br> dBc <br> dB <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> $\mathrm{pA} / \sqrt{ } \mathrm{Hz}$ |
| DC PERFORMANCE <br> Differential Input Offset Voltage <br> Differential Input Offset Voltage Drift <br> Common-Mode Offset Voltage <br> Common-Mode Offset Voltage Drift <br> Input Bias Current <br> Input Offset Current <br> Gain <br> Gain Error <br> Gain Error Drift | IN and REF <br> IN and REF <br> (OUT+- OUT-)/(IN+ - REF) |  | 0.2 0.1 2.2 0.2 2 0.1 0.01 | .5 .25 | mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> $\mu \mathrm{A}$ <br> $\mu \mathrm{A}$ <br> V/V <br> \% <br> $\% /{ }^{\circ} \mathrm{C}$ |
| INPUT CHARACTERISTICS <br> Input Resistance <br> Input Capacitance <br> Input Common-Mode Voltage Range Common-Mode Rejection Ratio | IN and REF IN and REF $\mathrm{V}_{\mathrm{cm}}= \pm 2.5 \mathrm{~V}$ | 0.1 | $\begin{aligned} & 12 \\ & 2 \\ & 110 \end{aligned}$ | 4 | $\begin{aligned} & \mathrm{M} \Omega \\ & \mathrm{pF} \\ & \mathrm{~V} \\ & \mathrm{~dB} \end{aligned}$ |
| OUTPUT CHARACTERISTICS <br> Output Voltage Swing: OUTOUT+ <br> Output Current <br> Capacitive Load Drive | $\begin{aligned} & R_{L}=1 \mathrm{k} \Omega \\ & R_{L}=1 \mathrm{k} \Omega \end{aligned}$ |  | $\begin{aligned} & 0.1 \text { to } 4.9 \\ & 0.1 \text { to } 4.9 \\ & 30 \end{aligned}$ |  | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~mA} \\ & \mathrm{pF} \end{aligned}$ |
| POWER SUPPLY <br> Operating Range <br> Quiescent Current <br> Quiescent Current-Disable <br> Power Supply Rejection Ration $\begin{aligned} & + \text { +PSRR } \\ & \text {-PSRR } \end{aligned}$ |  | 2.7 | 2.2 <br> 40 <br> 110 <br> 110 | 12 | V <br> mA <br> $\mu \mathrm{A}$ <br> dB <br> dB |
| DISABLE <br> $V_{\text {DIS }}$ High <br> VIIS Low Input Current V $_{\text {DIS }}=$ HIGH/LOW Turn-On Time Turn-Off Time |  |  | $\begin{aligned} & 3.8 \\ & 3.6 \\ & 5 / 12 \\ & 30 \\ & 0.65 \end{aligned}$ |  | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mu \mathrm{~A} \\ & \mu \mathrm{~s} \\ & \mu \mathrm{~s} \end{aligned}$ |

ADA4941-1
$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{Vs}= \pm 5 \mathrm{~V}$, unless otherwise noted.
Table 3.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DYNAMIC PERFORMANCE -3 dB Bandwidth <br> Overdrive Recovery Time Slew Rate Settling Time 0.0005\% | $\begin{aligned} & \mathrm{V}_{\mathrm{o}}=0.1 \mathrm{~V} \text { p-p } \\ & \mathrm{V}_{\mathrm{o}}=2.0 \mathrm{~V} \text { p-p } \\ & -5 \mathrm{~V} \text { to }+5 \mathrm{~V} \text { step overdrive } \\ & \mathrm{V}_{0}=2 \mathrm{~V} \text { step } \\ & \mathrm{V}_{0}=12 \mathrm{~V} \text { p-p step } \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 32.5 \\ & 7.5 \\ & 400 \\ & 26.5 \\ & 980 \end{aligned}$ |  | MHz <br> MHz <br> ns <br> V/ $\mu \mathrm{s}$ <br> ns |
| NOISE/DISTORTION PERFORMANCE THD <br> SNR <br> RTO Voltage Noise Input Current Noise | $\begin{aligned} & \mathrm{f}_{\mathrm{c}}=10 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=1 \mathrm{MHz}, \mathrm{~V}_{\mathrm{o}}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{f}_{\mathrm{c}}=100 \mathrm{kHz}, \mathrm{~V}_{\mathrm{o}}=4 \mathrm{Vp}-\mathrm{p}, \mathrm{fb}=2 \mathrm{MHz} \\ & \mathrm{f}=100 \mathrm{kHz} \\ & \mathrm{f}=100 \mathrm{kHz}, \mathrm{IN}+\text { and REF } \end{aligned}$ |  | $\begin{aligned} & 120 \\ & 74 \\ & 97 \end{aligned}$ |  | dBc <br> dBc <br> dB <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> $\mathrm{pA} / \sqrt{ } \mathrm{Hz}$ |
| DC PERFORMANCE <br> Differential Input Offset Voltage <br> Differential Input Offset Voltage Drift <br> Common-Mode Offset Voltage <br> Common-Mode Offset Voltage Drift <br> Input Bias Current <br> Input Offset Current <br> Gain <br> Gain Error <br> Gain Error Drift | IN+ and REF <br> IN+ and REF <br> (OUT+ - OUT-)/(IN+ - REF) |  | $\begin{aligned} & 0.2 \\ & 0.1 \\ & 2.2 \\ & 0.2 \\ & 2 \\ & 0.1 \\ & 0.01 \end{aligned}$ | $\begin{aligned} & 0.5 \\ & 0.25 \end{aligned}$ | mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> mV <br> $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ <br> $\mu \mathrm{A}$ <br> $\mu \mathrm{A}$ <br> V/V <br> \% <br> $\% /{ }^{\circ} \mathrm{C}$ |
| INPUT CHARACTERISTICS <br> Input Resistance <br> Input Capacitance <br> Input Common-Mode Voltage Range <br> Common-Mode Rejection Ratio | IN+ and REF IN+ and REF $\mathrm{V}_{\mathrm{cm}}= \pm 2.5 \mathrm{~V}$ | -4.9 | $\begin{aligned} & 12 \\ & 2 \\ & 110 \end{aligned}$ | +4 | $\mathrm{M} \Omega$ <br> pF <br> V <br> dB |
| OUTPUT CHARACTERISTICS <br> Output Voltage Swing: OUTOUT+ <br> Output Current Capacitive Load Drive | $\begin{aligned} & R_{L}=1 \mathrm{k} \Omega \\ & R_{L}=1 \mathrm{k} \Omega \end{aligned}$ |  | $\begin{aligned} & -4.9 \text { to }+4.9 \\ & -4.9 \text { to }+4.9 \\ & 40 \end{aligned}$ |  | V <br> V <br> mA <br> pF |
| POWER SUPPLY <br> Operating Range <br> Quiescent Current <br> Quiescent Current—Disable <br> Power Supply Rejection Ration $\begin{aligned} & + \text { +PSRR } \\ & \text {-PSRR } \end{aligned}$ |  | 2.7 | $\begin{aligned} & 2.5 \\ & 50 \\ & \\ & 110 \\ & 110 \end{aligned}$ | 12 | V mA $\mu \mathrm{A}$ dB dB |
| DISABLE <br> $V_{\text {DIS }}$ High <br> Vois Low <br> Input Current $\mathrm{V}_{\text {DIS }}=\mathrm{HIGH} / \mathrm{LOW}$ <br> Turn-On Time Turn-Off Time |  |  | $\begin{aligned} & 3.8 \\ & 3.6 \\ & 5 / 16 \\ & 30 \\ & 0.65 \end{aligned}$ |  | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mu \mathrm{~A} \\ & \mu \mathrm{~s} \\ & \mu \mathrm{~s} \end{aligned}$ |

## OUTLINE DIMENSIONS



Figure 1. 8-Lead Standard Small Outline Package Narrow Body [SOIC] (R-8)—Dimensions shown in millimeters and (inches)


Figure 2. 8-Lead Lead Frame Chip Scale Package [LFCSP], $3 \mathrm{~mm} \times 3 \mathrm{~mm}$ Body (CP-8-2)—Dimensions shown in millimeters

## ORDERING GUIDE

| Model | Temperature Range | Package Description | Package Option | Branding |
| :---: | :---: | :---: | :---: | :---: |
| ADA4941-1YRZ ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Small Outline Package (SOIC) | R-8 |  |
| ADA4941-1YRZ-RL ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Small Outline Package (SOIC) | R-8 |  |
| ADA4941-1YRZ-R71 | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Small Outline Package (SOIC) | R-8 |  |
| ADA4941-1YCPZ-R2 ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Lead Frame Chip Scale Package (LFCSP) | CP-8-2 | H9C |
| ADA4941-1YCPZ-RL ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Lead Frame Chip Scale Package (LFCSP) | CP-8-2 | H9C |
| ADA4941-1YCPZ-R71 | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | 8-Lead Lead Frame Chip Scale Package (LFCSP) | CP-8-2 | H9C |

${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.

