

25-BIT CONFIGURABLE REGISTERED BUFFER WITH ADDRESS-PARITY TEST

FEATURES

- Member of the Texas Instruments Widebus+™ Family
- Pinout Optimizes DDR2 DIMM PCB Layout
- Configurable as 25-Bit 1:1 or 14-Bit 1:2 Registered Buffer
- Chip-Select Inputs Gate the Data Outputs from Changing State and Minimizes System Power Consumption
- Output Edge-Control Circuitry Minimizes Switching Noise in an Unterminated Line
- Supports SSTL_18 Data Inputs
- Differential Clock (CLK and $\overline{\text{CLK}}$) Inputs
- Supports LVCMOS Switching Levels on the Control and RESET Inputs
- Checks Parity on DIMM-Independent Data Inputs
- Able to Cascade with a Second SN74SSTUB32866
- $\overline{\text{RESET}}$ Input Disables Differential Input Receivers, Resets All Registers, and Forces All Outputs Low, Except $\overline{\text{QERR}}$

DESCRIPTION

This 25-bit 1:1 or 14-bit 1:2 configurable registered buffer is designed for 1.7-V to 1.9-V VCC operation. In the 1:1 pinout configuration, only one device per DIMM is required to drive nine SDRAM loads. In the 1:2 pinout configuration, two devices per DIMM are required to drive 18 SDRAM loads.

All inputs are SSTL_18, except the reset ($\overline{\text{RESET}}$) and control (Cn) inputs, which are LVCMOS. All outputs are edge-controlled circuits optimized for unterminated DIMM loads and meet SSTL_18 specifications, except the open-drain error ($\overline{\text{QERR}}$) output.

The SN74SSTUB32866 operates from a differential clock (CLK and $\overline{\text{CLK}}$). Data are registered at the crossing of CLK going high and $\overline{\text{CLK}}$ going low.

The SN74SSTUB32866 accepts a parity bit from the memory controller on the parity bit (PAR_IN) input, compares it with the data received on the DIMM-independent D-inputs (D2–D3, D5–D6, D8–D25 when C0 = 0 and C1 = 0; D2–D3, D5–D6, D8–D14 when C0 = 0 and C1 = 1; or D1–D6, D8–D13 when C0 = 1 and C1 = 1) and indicates whether a parity error has occurred on the open-drain $\overline{\text{QERR}}$ pin (active low). The convention is even parity; i.e., valid parity is defined as an even number of ones across the DIMM-independent data inputs, combined with the parity input bit. To calculate parity, all DIMM-independent data inputs must be tied to a known logic state.

When used as a single device, the C0 and C1 inputs are tied low. In this configuration, parity is checked on the PAR_IN input signal, which arrives one cycle after the input data to which it applies. Two clock cycles after the data are registered, the corresponding partial-parity-out (PPO) and $\overline{\text{QERR}}$ signals are generated.

When used in pairs, the C0 input of the first register is tied low, and the C0 input of the second register is tied high. The C1 input of both registers are tied high. Parity, which arrives one cycle after the data input to which it applies, is checked on the PAR_IN input signal of the first device. Two clock cycles after the data are registered, the corresponding PPO and $\overline{\text{QERR}}$ signals are generated on the second device. The PPO output of the first register is cascaded to the PAR_IN of the second SN74SSTUB32866. The $\overline{\text{QERR}}$ output of the first SN74SSTUB32866 is left floating, and the valid error information is latched on the $\overline{\text{QERR}}$ output of the second SN74SSTUB32866.

ORDERING INFORMATION

T _A	PACKAGE ⁽¹⁾		ORDERABLE PART NUMBER	TOP-SIDE MARKING
0°C to 70°C	LFBGA–ZKE	Tape and reel	SN74SSTUB32866ZKER	SB866

(1) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

Widebus+ is a trademark of Texas Instruments.

DESCRIPTION (CONTINUED)

If an error occurs and the \overline{QERR} output is driven low, it stays latched low for a minimum of two clock cycles or until \overline{RESET} is driven low. If two or more consecutive parity errors occur, the \overline{QERR} output is driven low and latched low for a clock duration equal to the parity-error duration or until \overline{RESET} is driven low. The DIMM-dependent signals (\overline{DCKE} , \overline{DCS} , \overline{DODT} , and \overline{CSR}) are not included in the parity-check computation.

The C0 input controls the pinout configuration of the 1:2 pinout from register-A configuration (when low) to register-B configuration (when high). The C1 input controls the pinout configuration from 25-bit 1:1 (when low) to 14-bit 1:2 (when high). C0 and C1 should not be switched during normal operation. They should be hard-wired to a valid low or high level to configure the register in the desired mode. In the 25-bit 1:1 pinout configuration, the A6, D6, and H6 terminals are driven low and are do-not-use (DNU) pins.

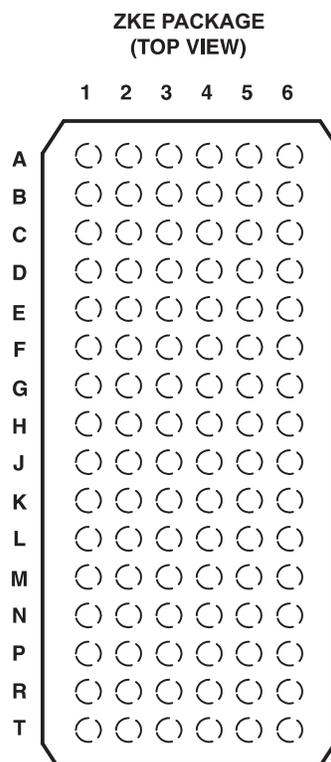
In the DDR2 RDIMM application, \overline{RESET} is specified to be completely asynchronous with respect to CLK and \overline{CLK} . Therefore, no timing relationship can be ensured between the two. When entering reset, the register is cleared, and the data outputs are driven low quickly, relative to the time required to disable the differential input receivers. However, when coming out of reset, the register becomes active quickly, relative to the time required to enable the differential input receivers. As long as the data inputs are low, and the clock is stable during the time from the low-to-high transition of \overline{RESET} until the input receivers are fully enabled, the design of the SN74SSTUB32866 ensures that the outputs remain low, thus ensuring there will be no glitches on the output.

To ensure defined outputs from the register before a stable clock has been supplied, \overline{RESET} must be held in the low state during power up.

The device supports low-power standby operation. When \overline{RESET} is low, the differential input receivers are disabled, and undriven (floating) data, clock, and reference voltage (V_{REF}) inputs are allowed. In addition, when \overline{RESET} is low, all registers are reset and all outputs are forced low, except \overline{QERR} . The LVC MOS \overline{RESET} and Cn inputs always must be held at a valid logic high or low level.

The device also supports low-power active operation by monitoring both system chip select (\overline{DCS} and \overline{CSR}) inputs and gates the Qn and PPO outputs from changing states when both \overline{DCS} and \overline{CSR} inputs are high. If either DCS or CSR input is low, the Qn and PPO outputs function normally. Also, if the internal low-power signal (LPS1) is high (one cycle after \overline{DCS} and \overline{CSR} go high), the device gates the \overline{QERR} output from changing states. If LPS1 is low, the \overline{QERR} output functions normally. The \overline{RESET} input has priority over the \overline{DCS} and \overline{CSR} control and, when driven low, forces the Qn and PPO outputs low and forces the \overline{QERR} output high. If the \overline{DCS} control functionality is not desired, the \overline{CSR} input can be hard-wired to ground, in which case the setup-time requirement for \overline{DCS} is the same as for the other D data inputs. To control the low-power mode with \overline{DCS} only, the \overline{CSR} input should be pulled up to V_{CC} through a pullup resistor.

The two V_{REF} pins (A3 and T3) are connected together internally by approximately 150 Ω . However, it is necessary to connect only one of the two V_{REF} pins to the external V_{REF} power supply. An unused V_{REF} pin should be terminated with a V_{REF} coupling capacitor.



Terminal Assignments for 1:1 Register-A (C0 = 0, C1 = 0)

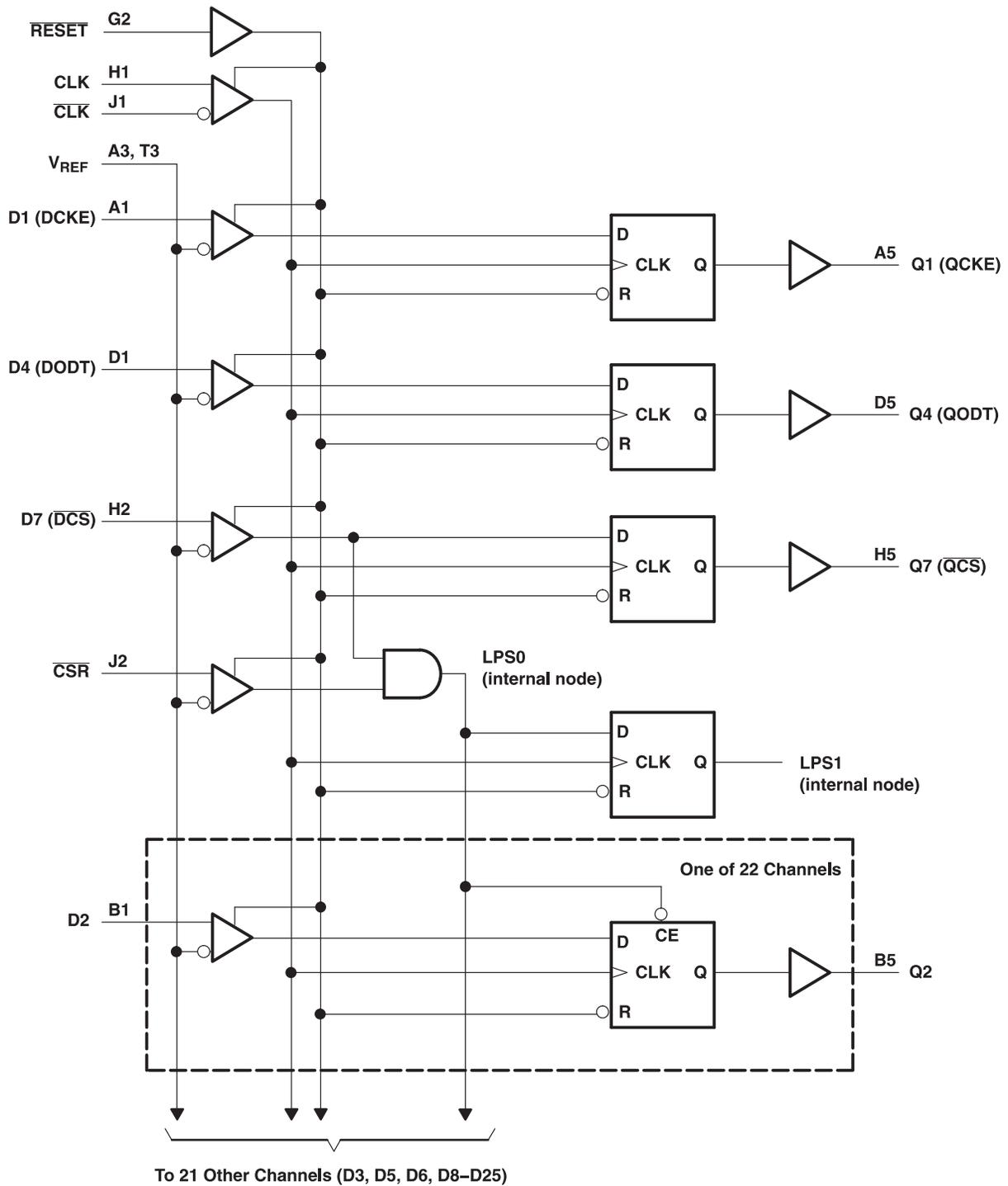
	1	2	3	4	5	6
A	D1 (DCKE)	PPO	V _{REF}	V _{CC}	Q1 (QCKE)	DNU
B	D2	D15	GND	GND	Q2	Q15
S	D3	D16	V _{CC}	V _{CC}	Q3	Q16
D	D4 (DODT)	QERR	GND	GND	Q4 (QODT)	DNU
E	D5	D17	V _{CC}	V _{CC}	Q5	Q17
F	D6	D18	GND	GND	Q6	Q18
G	PAR_IN	RESET	V _{CC}	V _{CC}	C1	C0
H	CLK	D7 (DCS)	GND	GND	Q7 (QCS)	DNU
J	CLK	CSR	V _{CC}	V _{CC}	NC	NC
K	D8	D19	GND	GND	Q8	Q19
L	D9	D20	V _{CC}	V _{CC}	Q9	Q20
M	D10	D21	GND	GND	Q10	Q21
N	D11	D22	V _{CC}	V _{CC}	Q11	Q22
P	D12	D23	GND	GND	Q12	Q23
R	D13	D24	V _{CC}	V _{CC}	Q13	Q24
T	D14	D25	V _{REF}	V _{CC}	Q14	Q25

Each pin name in parentheses indicates the DDR2 DIMM signal name.

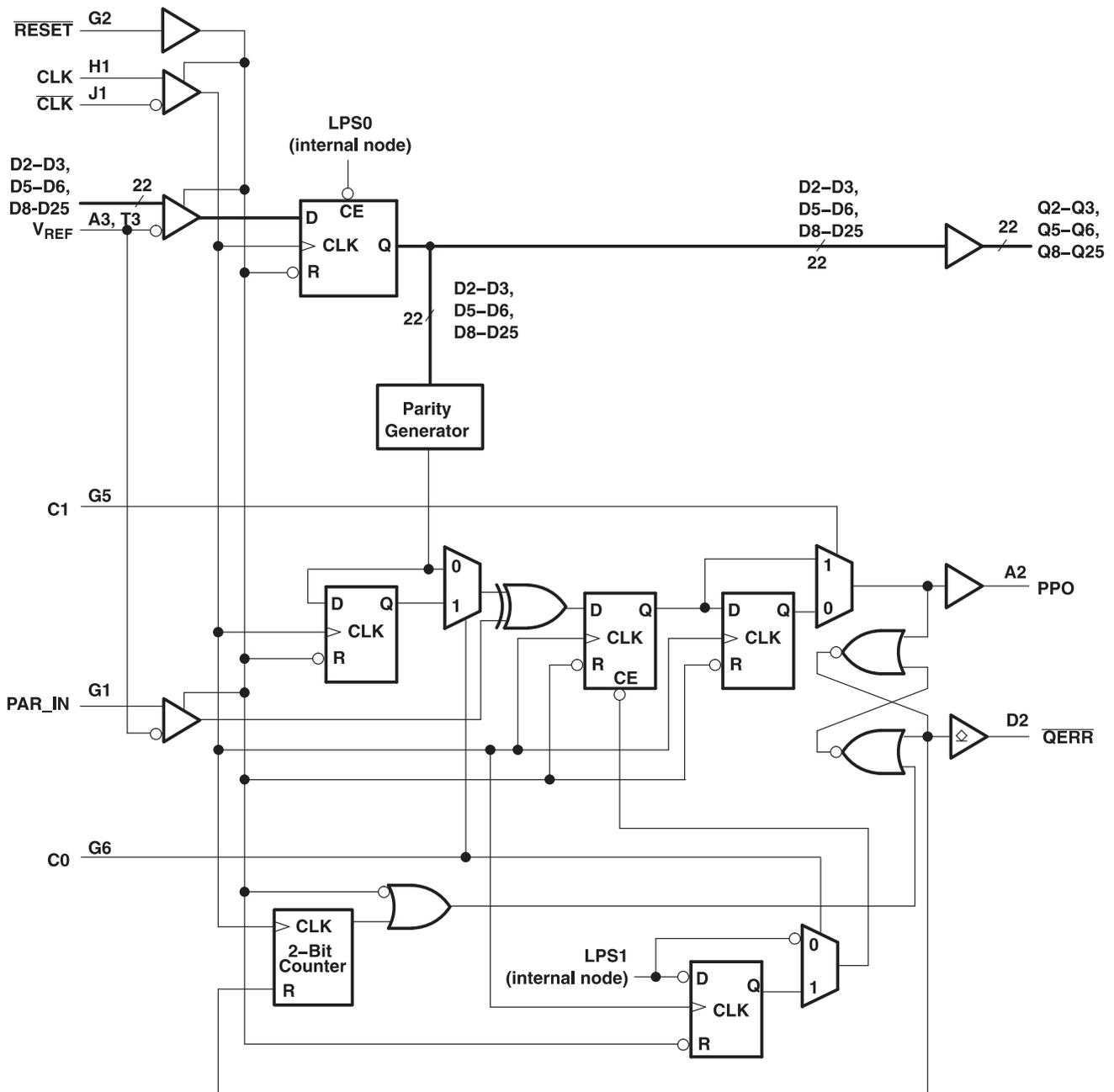
DNU - Do not use

NC - No internal connection

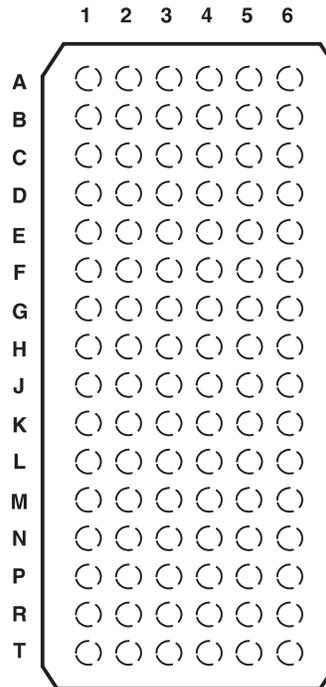
Logic Diagram for 1:1 Register Configuration (Positive Logic); C0 = 0, C1 = 0



Parity Logic Diagram for 1:1 Register Configuration (Positive Logic); C0 = 0, C1 = 0



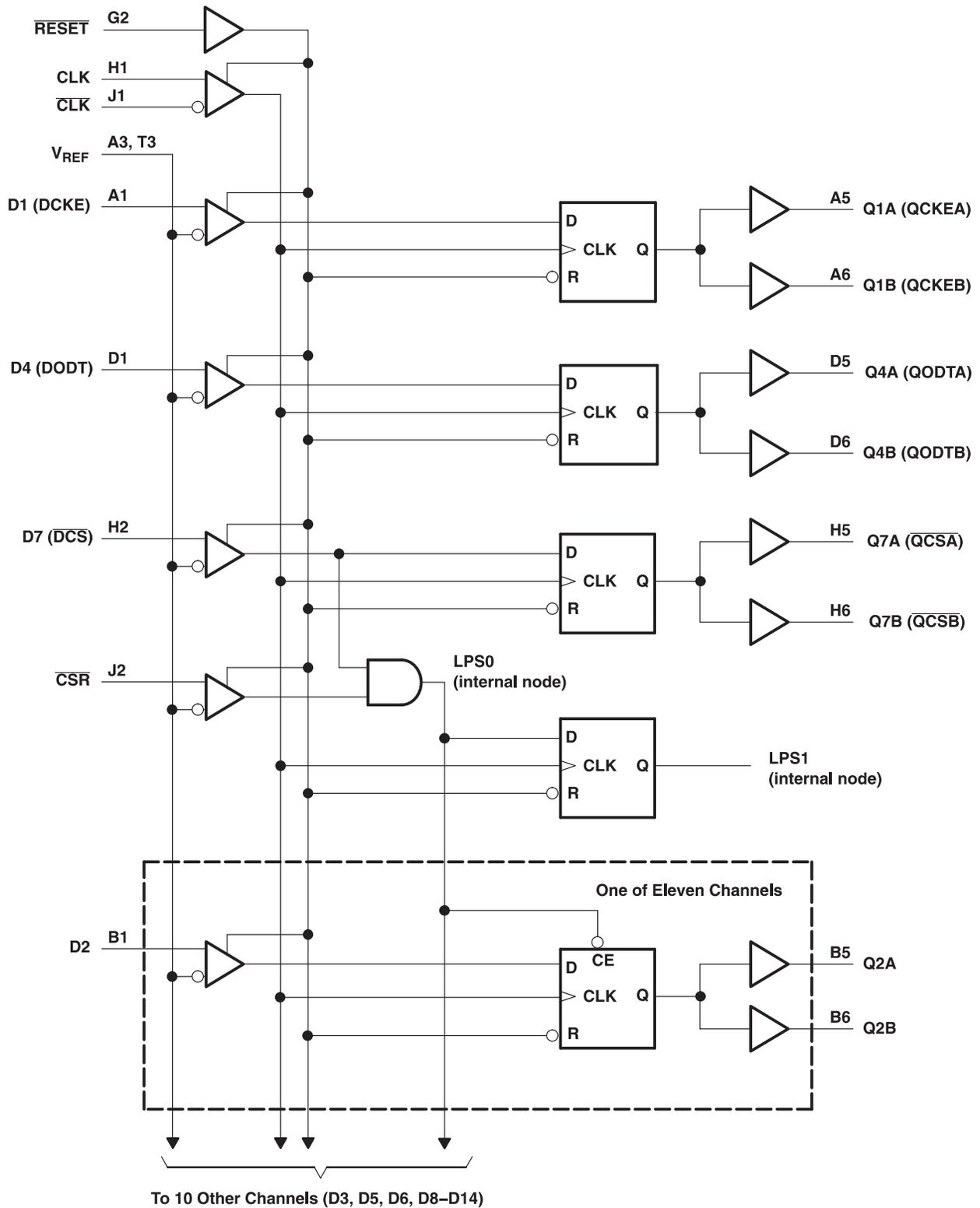
**ZKE PACKAGE
(TOP VIEW)**



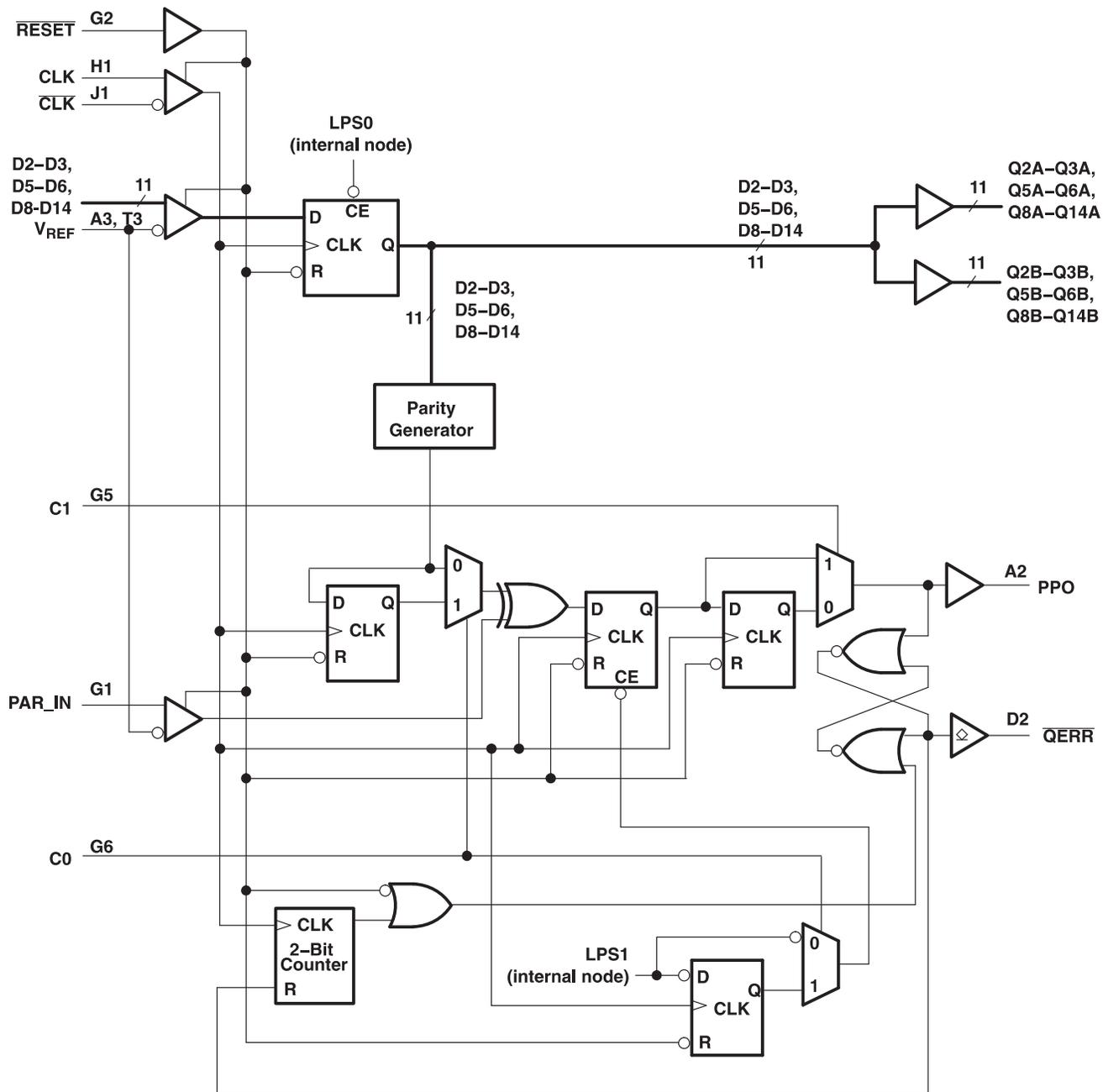
	1	2	3	4	5	6
A	D1 (DCKE)	PPO	V _{REF}	V _{CC}	Q1A (QCKEA)	Q1B (QCKEB)
B	D2	DNU	GND	GND	Q2A	Q2B
S	D3	DNU	V _{CC}	V _{CC}	Q3A	Q3B
D	D4 (DODT)	\overline{QERR}	GND	GND	Q4A (QODTA)	Q4B(QODTB)
E	D5	DNU	V _{CC}	V _{CC}	Q5A	Q5B
F	D6	DNU	GND	GND	Q6A	Q6B
G	PAR_IN	\overline{RESET}	V _{CC}	V _{CC}	C1	C0
H	CLK	D7 (\overline{DCS})	GND	GND	Q7A (\overline{QCSA})	Q7B (\overline{QCSB})
J	\overline{CLK}	\overline{CSR}	V _{CC}	V _{CC}	NC	NC
K	D8	DNU	GND	GND	Q8A	Q8B
L	D9	DNU	V _{CC}	V _{CC}	Q9A	Q9B
M	D10	DNU	GND	GND	Q10A	Q10B
N	D11	DNU	V _{CC}	V _{CC}	Q11A	Q11B
P	D12	DNU	GND	GND	Q12A	Q12B
R	D13	DNU	V _{CC}	V _{CC}	Q13A	Q13B
T	D14	DNU	V _{REF}	V _{CC}	Q14A	Q14B

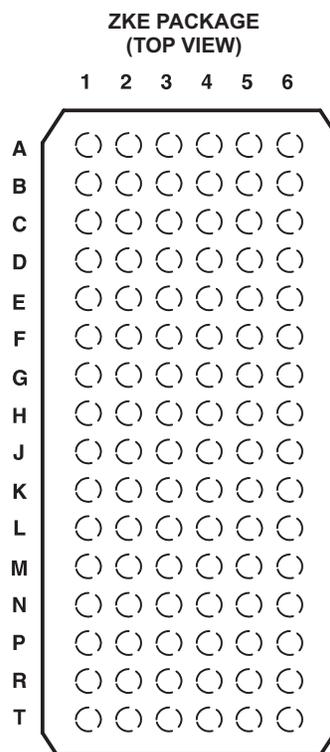
Each pin name in parentheses indicates the DDR2 DIMM signal name.
 DNU - Do not use
 NC - No internal connection

Logic Diagram for 1:2 Register-A Configuration (Positive Logic); C0 = 0, C1 = 1



Parity Logic Diagram for 1:2 Register-A Configuration (Positive Logic); C0 = 0, C1 = 1



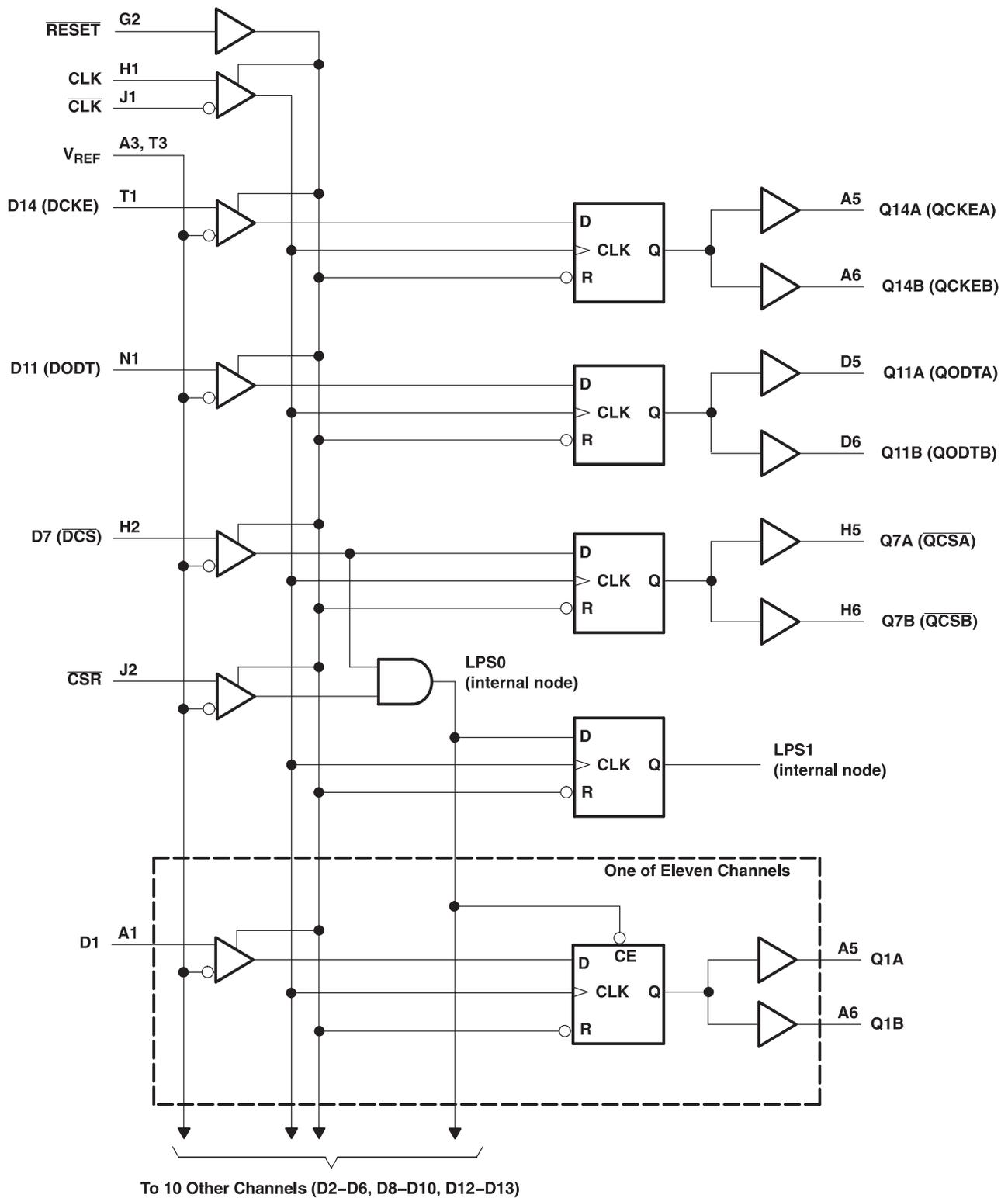


Terminal Assignments for 1:2 Register-b (C0 = 1, C1 = 1)

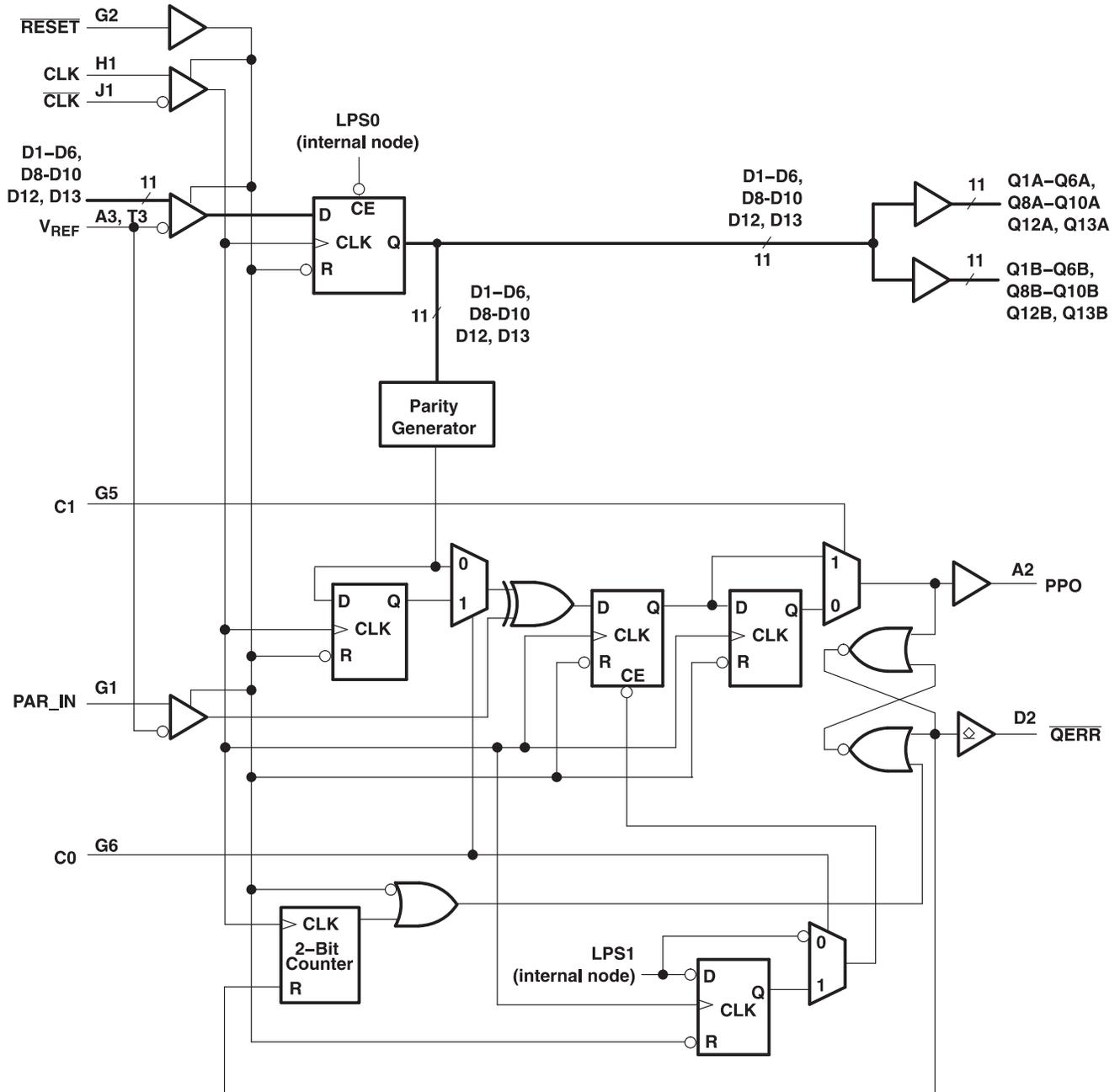
	1	2	3	4	5	6
A	D1	PPO	V _{REF}	V _{CC}	Q1A	Q1B
B	D2	DNU	GND	GND	Q2A	Q2B
S	D3	DNU	V _{CC}	V _{CC}	Q3A	Q3B
D	D4	\overline{QERR}	GND	GND	Q4A	Q4B
E	D5	DNU	V _{CC}	V _{CC}	Q5A	Q5B
F	D6	DNU	GND	GND	Q6A	Q6B
G	PAR_IN	\overline{RESET}	V _{CC}	V _{CC}	C1	C0
H	CLK	D7 (DCS)	GND	GND	Q7A (QC _{SA})	Q7B (QC _{SB})
J	\overline{CLK}	\overline{CSR}	V _{CC}	V _{CC}	NC	NC
K	D8	DNU	GND	GND	Q8A	Q8B
L	D9	DNU	V _{CC}	V _{CC}	Q9A	Q9B
M	D10	DNU	GND	GND	Q10A	Q10B
N	D11 (DODT)	DNU	V _{CC}	V _{CC}	Q11A (QODTA)	Q11B (QODTB)
P	D12	DNU	GND	GND	Q12A	Q12B
R	D13	DNU	V _{CC}	V _{CC}	Q13A	Q13B
T	D14 (DCKE)	DNU	V _{REF}	V _{CC}	Q14A (QCKEA)	Q14B (QCKEB)

Each pin name in parentheses indicates the DDR2 DIMM signal name.
 DNU - Do not use
 NC - No internal connection

Logic Diagram for 1:2 Register-B Configuration C0 = 1, C1 = 1



Parity Logic Diagram for 1:2 Register-b Configuration (Positive Logic); C0 = 1, C1 = 1



TERMINAL FUNCTIONS

TERMINAL NAME	DESCRIPTION	ELECTRICAL CHARACTERISTICS
GND	Ground	Ground input
V _{CC}	Power-supply voltage	1.8 V nominal
V _{REF}	Input reference voltage	0.9 V nominal
CLK	Positive master clock input	Differential input
$\overline{\text{CLK}}$	Negative master clock input	Differential input
C0, C1	Configuration control input. Register A or Register B and 1:1 mode or 1:2 mode select.	LVC MOS inputs
RESET	Asynchronous reset input. Resets registers and disables V _{REF} , data, and clock differential-input receivers. When RESET is low, all Q outputs are forced low and the QERR output is forced high.	LVC MOS input
D1-D25	Data input. Clocked in on the crossing of the rising edge of CLK and the falling edge of $\overline{\text{CLK}}$.	SSTL ₁₈ inputs
CSR, $\overline{\text{DCS}}$	Chip select inputs. Disables D1–D25 ⁽¹⁾ outputs switching when both inputs are high	SSTL ₁₈ inputs
DODT	The outputs of this register bit will not be suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control.	SSTL ₁₈ input
DCKE	The outputs of this register bit will not be suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control.	SSTL ₁₈ input
PAR_IN	Parity input. Arrives one clock cycle after the corresponding data input. Pulldown resistor of typical 150k Ω to GND.	SSTL ₁₈ input pulldown
Q1–Q25 ⁽²⁾	Data outputs that are suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control.	1.8 V CMOS outputs
PPO	Partial parity out. Indicates odd parity of inputs D1–D25. ⁽¹⁾	1.8 V CMOS output
$\overline{\text{QCS}}$	Data output that will not be suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control	1.8 V CMOS output
QODT	Data output that will not be suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control	1.8 V CMOS output
QCKE	Data output that will not be suspended by the $\overline{\text{DCS}}$ and $\overline{\text{CSR}}$ control	1.8 V CMOS output
QERR	Output error bit. Timing is determined by the device mode.	Open-drain output
NC	No internal connection	
DNU	Do not use. Inputs are in standby-equivalent mode, and outputs are driven low.	

- (1) Data inputs = D2, D3, D5, D6, D8-D25 when C0 = 0 and C1 = 0
 Data inputs = D2, D3, D5, D6, D8-D14 when C0 = 0 and C1 = 1
 Data inputs = D1-D6, D8-D10, D12, D13 when C0 = 1 and C1 = 1.D
- (2) Data outputs = Q2, Q3, Q5, Q6, Q8-Q25 when C0 = 0 and C1 = 0
 Data outputs = Q2, Q3, Q5, Q6, Q8-Q14 when C0 = 0 and C1 = 1
 Data outputs = Q1-Q6, Q8-Q10, Q12, Q13 when C0 = 1 and C1 = 1.

FUNCTION TABLE

INPUTS						OUTPUTS
RESET	$\overline{\text{DCS}}$	$\overline{\text{CSR}}$	CLK	$\overline{\text{CLK}}$	D _n	Q _n
H	L	X	↑	↓	L	L
H	L	X	↑	↓	H	H
H	X	L	↑	↓	L	L
H	X	L	↑	↓	H	H
H	H	H	↑	↓	X	Q ₀
H	X	X	L or H	L or H	X	Q ₀
L	X or Floating	X or Floating	X or Floating	X or Floating	X or Floating	L

FUNCTION TABLE

INPUTS				OUTPUTS
RESET	CLK	$\overline{\text{CLK}}$	DCKE, $\overline{\text{DCS}}$, DODT	QCKE, $\overline{\text{QCS}}$, QODT
H	↑	↓	H	H
H	↑	↓	L	L
H	L or H	L or H	X	Q ₀
L	X or Floating	X or Floating	X or Floating	L

PARITY AND STANDBY FUNCTION

INPUTS							OUTPUTS	
RESET	CLK	CLK	DCS	CSR	Σ OF INPUTS = H D1–D25 ⁽¹⁾	PAR_IN ⁽²⁾	PPO	QERR ⁽³⁾
H	↑	↓	L	X	Even	L	L	H
H	↑	↓	L	X	Odd	L	H	L
H	↑	↓	L	X	Even	H	H	L
H	↑	↓	L	X	Odd	H	L	H
H	↑	↓	H	L	Even	L	L	H
H	↑	↓	H	L	Odd	L	H	L
H	↑	↓	H	L	Even	H	H	L
H	↑	↓	H	L	Odd	H	L	H
H	↑	↓	H	H	X	X	PPO ₀	QERR ₀
H	L or H	L or H	X	X	X	X	PPO ₀	QERR ₀
L	X or Floating	X or Floating	X or Floating	X or Floating	X	X or Floating	L	H

- (1) Data inputs = D2-D3, D5-D6, D8-D25 when C0 = 0 and C1 = 0
Data inputs = D2-D3, D5-D6, D8-D14 when C0 = 0 and C1 = 1
Data inputs = D1-D6, D8-D10, D12, D13 when C0 = 1 and C1 = 1
- (2) PAR_IN arrives one clock cycle (C0 = 0) or two clock cycles (C0 = 1) after the data to which it applies.
- (3) This transition assumes that QERR is high at the crossing of CLK going high and CLK going low. If QERR goes low, it stays latched low for a minimum of two clock cycles or until RESET is driven low. If two or more consecutive parity errors occur, the QERR output is driven low and latched low for a clock duration equal to the parity duration or until RESET is driven low.

PARITY ERROR DETECT IN LOW-POWER MODE⁽¹⁾

INPUT-DATA ERROR OCCURRENCE ⁽²⁾	1:1 MODE (C0 = 0, C1 = 0)		1:2 REGISTER-A MODE (C0 = 0, C1 = 1)		1:2 REGISTER-B MODE (C0 = 1, C1 = 1)		CASCADED MODE (Registers A and B)	
	PPO DURATION ⁽³⁾	QERR DURATION ⁽³⁾	PPO DURATION ⁽³⁾	QERR DURATION ⁽³⁾	PPO DURATION ⁽³⁾	QERR DURATION ⁽³⁾	PPO DURATION ⁽³⁾	QERR DURATION ⁽³⁾
n – 4	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles
n – 3	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles
n – 2	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles	1 Cycle	2 Cycles
n – 1	LPM + 2 Cycles	LPM + 2 Cycles	LPM + 1 Cycle	LPM + 1 Cycle	LPM + 2 Cycles	LPM + 2 Cycles	LPM + 2 Cycles	LPM + 2 Cycles
n	Not detected	Not detected	Not detected	Not detected	Not detected	Not detected	Not detected	Not detected

- (1) If a parity error occurs before the device enters the low-power mode (LPM), the behavior of PPO and QERR is dependent on the mode of the device and the position of the parity error occurrence. This table illustrates the low-power-mode effect on parity detect. The low-power mode is activated on the n clock cycle when DCS and CSR go high.
- (2) The clock-edge position of a one cycle data-input error relative to the clock-edge (n) which initiates LPM at the DCS and CSR inputs.
- (3) If an error occurs, then QERR output may be driven low and the PPO output driven high. These columns show the clock duration for which the PPO signal will be high.

ABSOLUTE MAXIMUM RATINGSover operating free-air temperature range (unless otherwise noted) ⁽¹⁾

		VALUE	UNIT	
V _{CC}	Supply voltage range	–0.5 to 2.5	V	
V _I	Input voltage range ⁽²⁾⁽³⁾	–0.5 to V _{CC} + 0.5	V	
V _O	Output voltage range ⁽²⁾⁽³⁾	–0.5 to V _{CC} + 0.5	V	
I _{IK}	Input clamp current, (V _I < 0 or V _I > V _{CC})	±50	mA	
I _{OK}	Output clamp current, (V _O < 0 or V _O > V _{CC})	±50	mA	
I _O	Continuous output current (V _O = 0 to V _{CC})	±50	mA	
I _{CCC}	Continuous current through each V _{CC} or GND	±100	mA	
R _{θJA}	Thermal impedance, junction-to-ambient ⁽⁴⁾	No airflow	39.8	K/W
		Airflow 150 ft/min	34.1	
		Airflow 250 ft/min	33.6	
		Airflow 500 ft/min	32.5	
R _{θJB}	Thermal resistance, junction-to-board ⁽⁴⁾	No airflow	14.5	
T _{stg}	Storage temperature range	–65 to 150	°C	

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

(3) This value is limited to 2.5 V maximum.

(4) The package thermal impedance is calculated in accordance with JEDEC 51-7.

RECOMMENDED OPERATING CONDITIONS⁽¹⁾

		MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage	1.7		1.9	V
V _{REF}	Reference voltage	0.49 × V _{CC}	0.5 × V _{CC}	0.51 × V _{CC}	V
V _{TT}	Termination voltage	V _{REF} –40 mV	V _{REF}	V _{REF} + 40 mV	V
V _I	Input voltage	0		V _{CC}	V
V _{IH}	AC high-level input voltage	Data inputs, $\overline{\text{CSR}}$, PAR_IN	V _{REF} + 250 mV		V
V _{IL}	AC low-level input voltage	Data inputs, $\overline{\text{CSR}}$, PAR_IN		V _{REF} –250 mV	V
V _{IH}	DC high-level input voltage	Data inputs, $\overline{\text{CSR}}$, PAR_IN	V _{REF} + 125 mV		V
V _{IL}	DC low-level input voltage	Data inputs, $\overline{\text{CSR}}$, PAR_IN		V _{REF} –125 mV	V
V _{IH}	High-level input voltage	$\overline{\text{RESET}}$, C _n	0.65 × V _{CC}		V
V _{IL}	Low-level input voltage	$\overline{\text{RESET}}$, C _n		0.35 × V _{CC}	V
V _{ICR}	Common-mode input voltage range	CLK, $\overline{\text{CLK}}$	0.675	1.125	V
V _{I(PP)}	Peak-to-peak input voltage	CLK, $\overline{\text{CLK}}$	600		mV
I _{OH}	High-level output current	Q outputs, PPO		–8	mA
I _{OL}	Low-level output current	Q outputs, PPO		8	mA
		$\overline{\text{QERR}}$ output	30		
T _A	Operating free-air temperature	0		70	°C

(1) The $\overline{\text{RESET}}$ and C_n inputs of the device must be held at valid logic voltage levels (not floating) to ensure proper device operation. The differential inputs must not be floating unless $\overline{\text{RESET}}$ is low. See the TI application report, *Implications of Slow or Floating CMOS Inputs* (SCBA004).

ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V _{CC}	MIN	TYP ⁽¹⁾	MAX	UNIT
V _{OH}	Q outputs, PPO	I _{OH} = -100 μA	1.7V to 1.9V	V _{CC} -0.2			V
		I _{OH} = -6 mA	1.7V	1.3			
V _{OL}	Q outputs, PPO	I _{OL} = 100 μA	1.7V to 1.9V	0.2			V
		I _{OL} = 6 mA	1.7V	0.4			
	$\overline{\text{QERR}}$ output	I _{OL} = 25 mA	1.7V	0.5			
I _I	PAR_IN	V _I = GND	1.9V	-5			μA
		V _I = V _{CC}		25			
	All other inputs ⁽²⁾	V _I = V _{CC} or GND		±5			
I _{OZ}	$\overline{\text{QERR}}$ output	VO = V _{CC} or GND	1.9V	±10			μA
I _{CC}	Static standby	$\overline{\text{RESET}} = \text{GND}$	1.9V	200			μA
	Static operating	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)}		I _O = 0	40		
I _{CCD}	Dynamic operating – clock only	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching 50% duty cycle	I _O = 0	1.8V	45		μA/MHz
	Dynamic operating – per each data input, 1:1 configuration	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching 50% duty cycle, one data input			43		μA clock MHz/ D input
	Dynamic operating – per each data input, 1:2 configuration	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching at one-half clock frequency, 50% duty cycle			60		
I _{CCDLP}	Chip-select-enabled low-power active mode – clock only	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching 50% duty cycle	I _O = 0	1.8V	45		μA/MHz
	Chip-select-enabled low-power active mode - 1:1 configuration	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching 50% duty cycle, one data input			2		μA clock MHz/ D input
	Chip-select-enabled low-power active mode – 1:2 configuration	$\overline{\text{RESET}} = V_{CC}$, V _I = V _{IH(AC)} or V _{IL(AC)} , CLK and $\overline{\text{CLK}}$ switching at one-half clock frequency, 50% duty cycle			3		
C _i	Data inputs, $\overline{\text{CSR}}$, PAR_IN	V _I = V _{REF} ± 250 mV	1.8V	2.5	3	3.5	pF
	CLK, $\overline{\text{CLK}}$	V _{ICR} = 0.9 V, V _{I(PP)} = 600 mV		2		3	
	$\overline{\text{RESET}}$	V _I = V _{CC} or GND		4			

(1) All typical values are at V_{CC} = 1.8 V, T_A = 25°C.

(2) Each V_{REF} pin (A3 or T3) should be tested independently, with the other (untested) pin open.

TIMING REQUIREMENTS

over recommended operating free-air temperature range (unless otherwise noted) (see [Figure 2](#) and ⁽¹⁾)

		$V_{CC} = 1.8\text{ V} \pm 0.1\text{ V}$		UNIT
		MIN	MAX	
f _{clock}	Clock frequency	410		MHz
t _w	Pulse duration, CLK, $\overline{\text{CLK}}$ high or low	1		ns
t _{act}	Differential inputs active time ⁽²⁾	10		ns
t _{inact}	Differential inputs inactive time ⁽³⁾	15		ns
t _{su}	Setup time	$\overline{\text{DCS}}$ before CLK \uparrow , $\overline{\text{CLK}}$ \downarrow , $\overline{\text{CSR}}$ high; $\overline{\text{CSR}}$ before CLK \uparrow , $\overline{\text{CLK}}$ \downarrow , $\overline{\text{DCS}}$ high	600	ps
		$\overline{\text{DCS}}$ before CLK \uparrow , $\overline{\text{CLK}}$ \downarrow , $\overline{\text{CSR}}$ low	500	
		DODT, DCKE, and Data before CLK \uparrow , $\overline{\text{CLK}}$ \downarrow	500	
		PAR_IN before CLK \uparrow , $\overline{\text{CLK}}$ \downarrow	500	
t _h	Hold time	$\overline{\text{DCS}}$, DODT, DCKE, and Data after CLK \uparrow , $\overline{\text{CLK}}$ \downarrow	400	ps
		PAR_IN after CLK \uparrow , $\overline{\text{CLK}}$ \downarrow	400	

(1) All inputs slew rate is 1 V/ns \pm 20%.

(2) V_{REF} must be held at a valid input level, and data inputs must be held low for a minimum time of t_{act} max, after $\overline{\text{RESET}}$ is taken high.

(3) V_{REF} , data, and clock inputs must be held at valid voltage levels (not floating) for a minimum time of t_{inact} max, after $\overline{\text{RESET}}$ is taken low.

SWITCHING CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		FROM (INPUT)	TO (OUTPUT)	$V_{CC} = 1.8\text{ V} \pm 0.1\text{ V}$		UNIT
				MIN	MAX	
f _{max}	See Figure 2			410		MHz
t _{pdm}	Production test, See Figure 1	CLK and $\overline{\text{CLK}}$	Q	0.4	0.8	ns
t _{pd}	See Figure 5	CLK and $\overline{\text{CLK}}$	PPO	0.6	1.6	ns
t _{PLH}	See Figure 4	CLK and $\overline{\text{CLK}}$	$\overline{\text{QERR}}$	1.2	2.4	ns
t _{PHL}				1	2.0	
t _{RPHL} ⁽¹⁾	See Figure 2	RESET	Q	3		ns
t _{RPHL}	See Figure 5		PPO	3		
t _{RPLH}	See Figure 5		$\overline{\text{QERR}}$	3		

(1) Includes 350-ps test-load transmission-line delay.

OUTPUT SLEW RATES

over recommended operating free-air temperature range (unless otherwise noted) (see [Figure 2](#))

PARAMETER	FROM	TO	$V_{CC} = 1.8\text{ V} \pm 0.1\text{ V}$		UNIT
			MIN	MAX	
dV/dt _r	20%	80%	1	4	V/ns
dV/dt _f	80%	20%	1	4	V/ns
dV/dt Δ ⁽¹⁾	20% or 80%	80% or 20%	1		V/ns

(1) Difference between dV/dt_r (rising edge rate) and dV/dt_f (falling edge rate).

PARAMETER MEASUREMENT INFORMATION

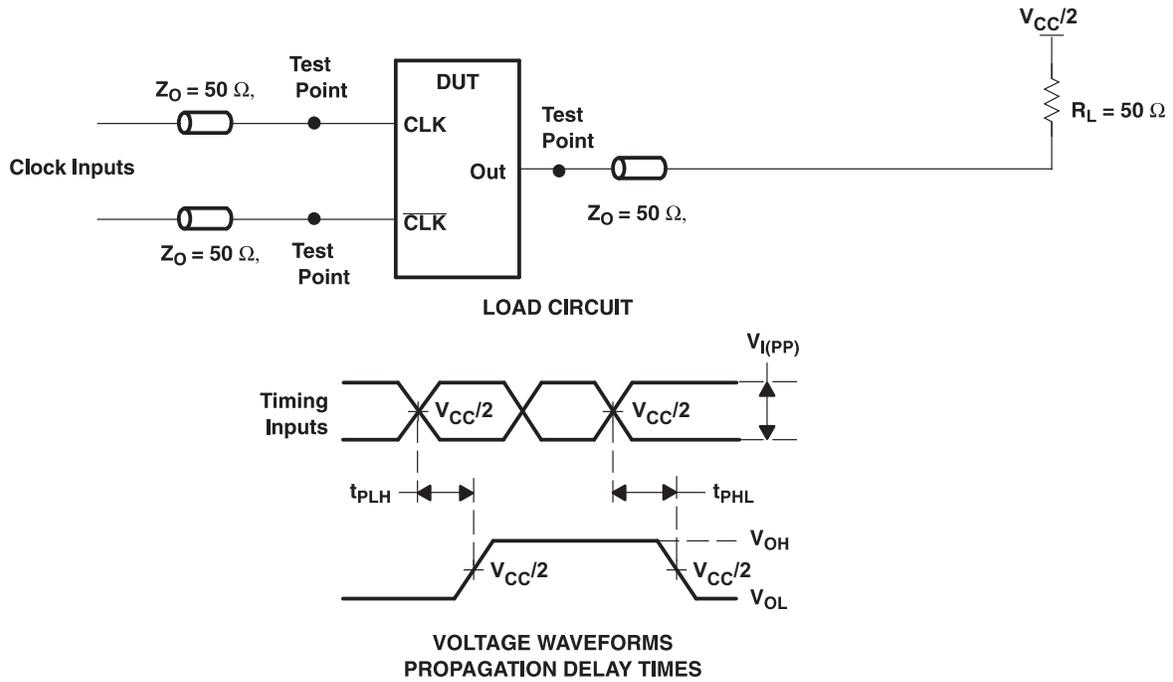
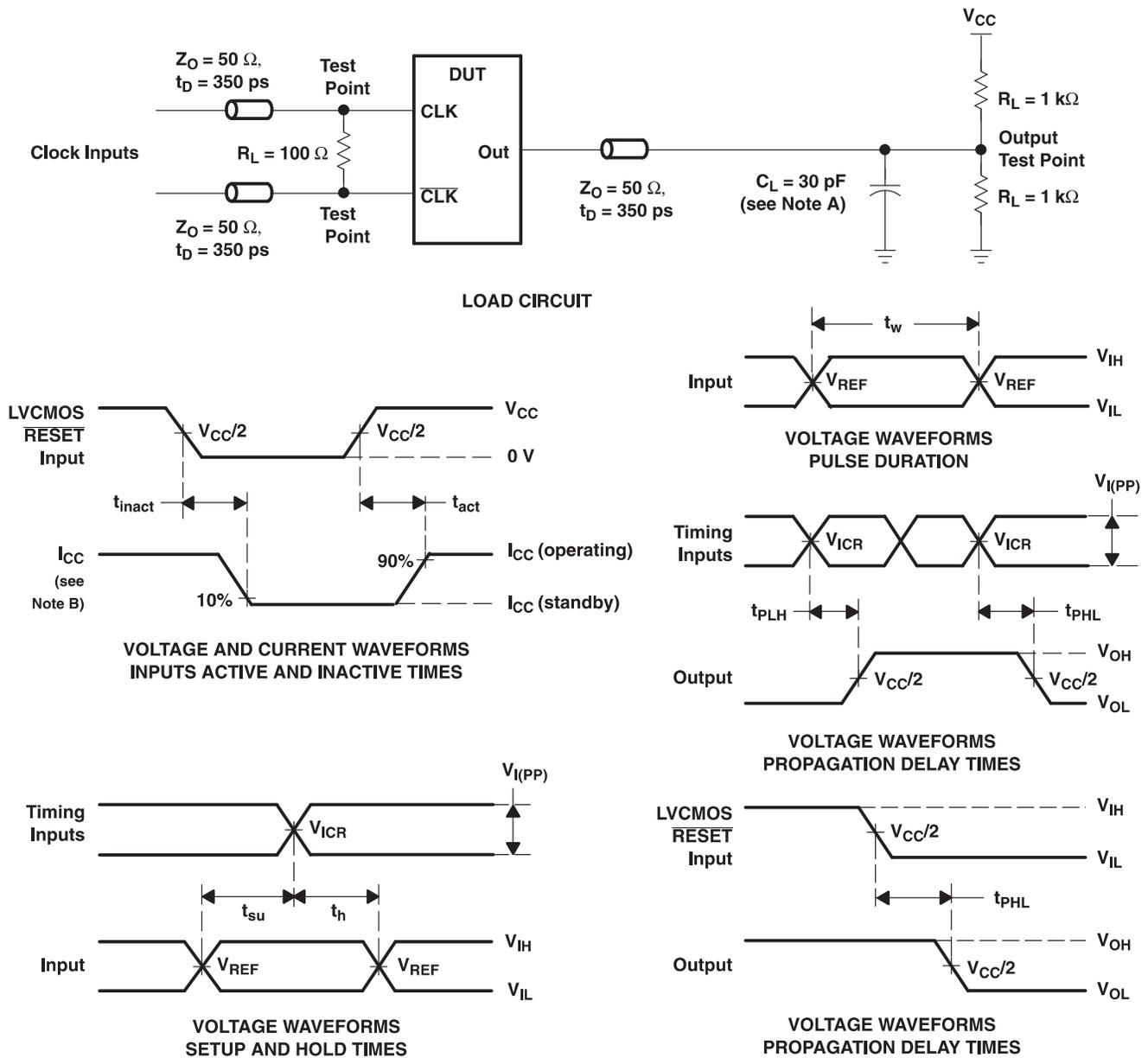


Figure 1. Output Load For Production Test

PROPAGATION DELAY (Design Goal as per JEDEC Specification)

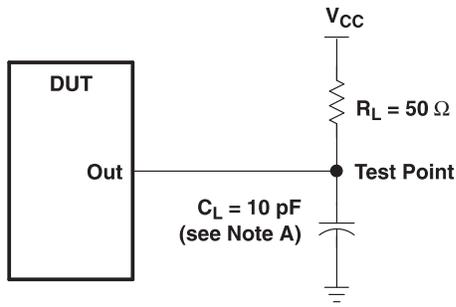
PARAMETER	FROM (INPUT)	TO (OUTPUT)	$V_{CC} = 1.8 V \pm 0.1 V$		UNIT
			MIN	MAX	
$t_{pdm}^{(1)}$	CLK and \overline{CLK}	Q	1.1	1.5	ns
$t_{pdmss}^{(1)}$	CLK and \overline{CLK}	Q		1.6	ns

(1) Includes 350 psi test-load transmission delay line

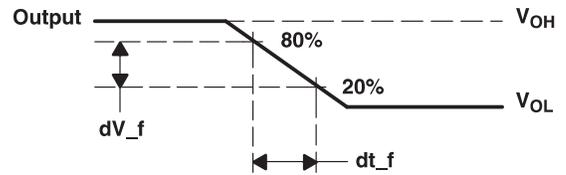


- NOTES:
- A. C_L includes probe and jig capacitance.
 - B. I_{CC} tested with clock and data inputs held at V_{CC} or GND, and $I_O = 0 \text{ mA}$.
 - C. All input pulses are supplied by generators having the following characteristics: $PRR \leq 10 \text{ MHz}$, $Z_0 = 50 \Omega$, input slew rate = $1 \text{ V/ns} \pm 20\%$ (unless otherwise noted).
 - D. The outputs are measured one at a time, with one transition per measurement.
 - E. $V_{REF} = V_{TT} = V_{CC}/2$
 - F. $V_{IH} = V_{REF} + 250 \text{ mV}$ (ac voltage levels) for differential inputs. $V_{IH} = V_{CC}$ for LVC MOS input.
 - G. $V_{IL} = V_{REF} - 250 \text{ mV}$ (ac voltage levels) for differential inputs. $V_{IL} = \text{GND}$ for LVC MOS input.
 - H. $V_{I(PP)} = 600 \text{ mV}$
 - I. t_{PLH} and t_{PHL} are the same as t_{pd} .

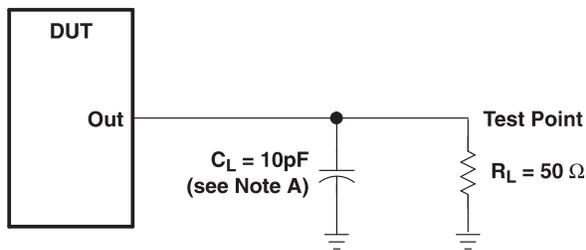
Figure 2. Data Output Load Circuit and Voltage Waveforms



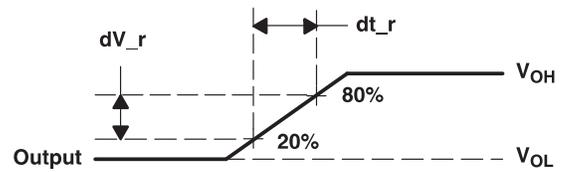
LOAD CIRCUIT
HIGH-TO-LOW SLEW-RATE MEASUREMENT



VOLTAGE WAVEFORMS
HIGH-TO-LOW SLEW-RATE MEASUREMENT



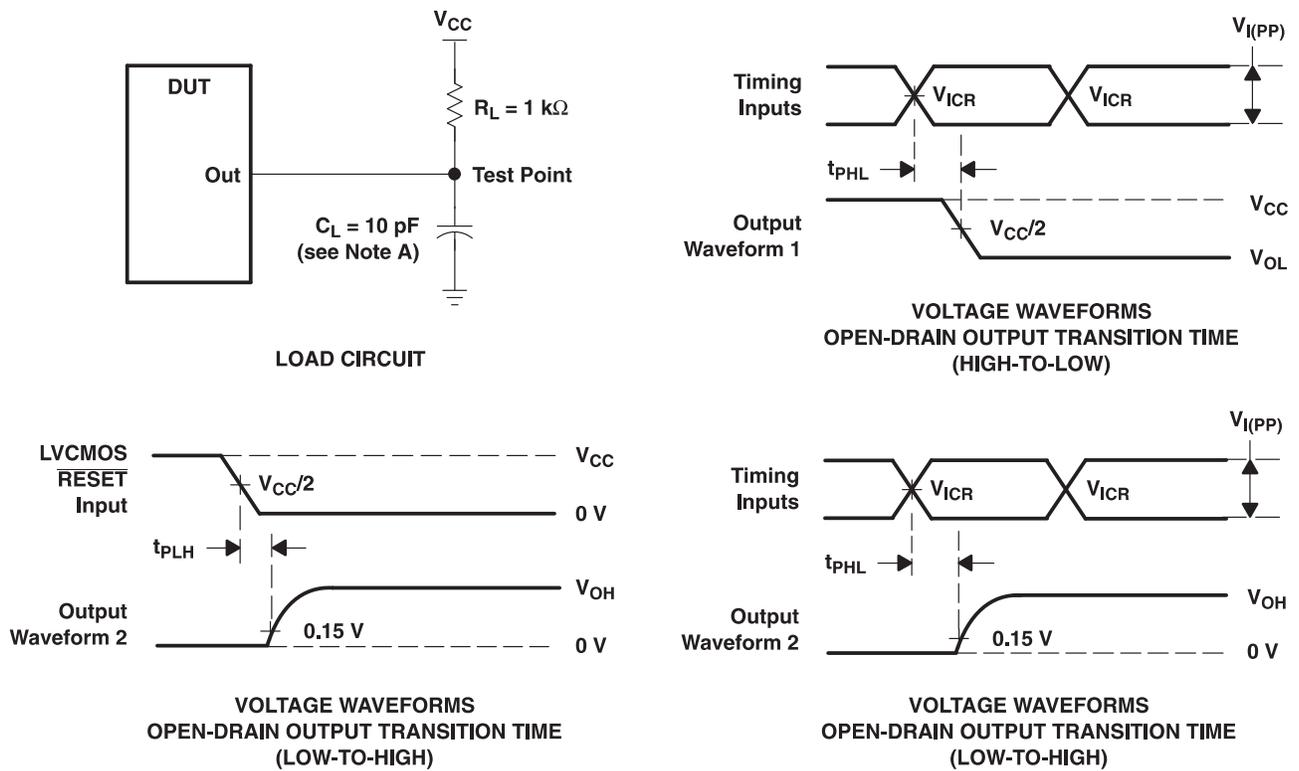
LOAD CIRCUIT
LOW-TO-HIGH SLEW-RATE MEASUREMENT



VOLTAGE WAVEFORMS
LOW-TO-HIGH SLEW-RATE MEASUREMENT

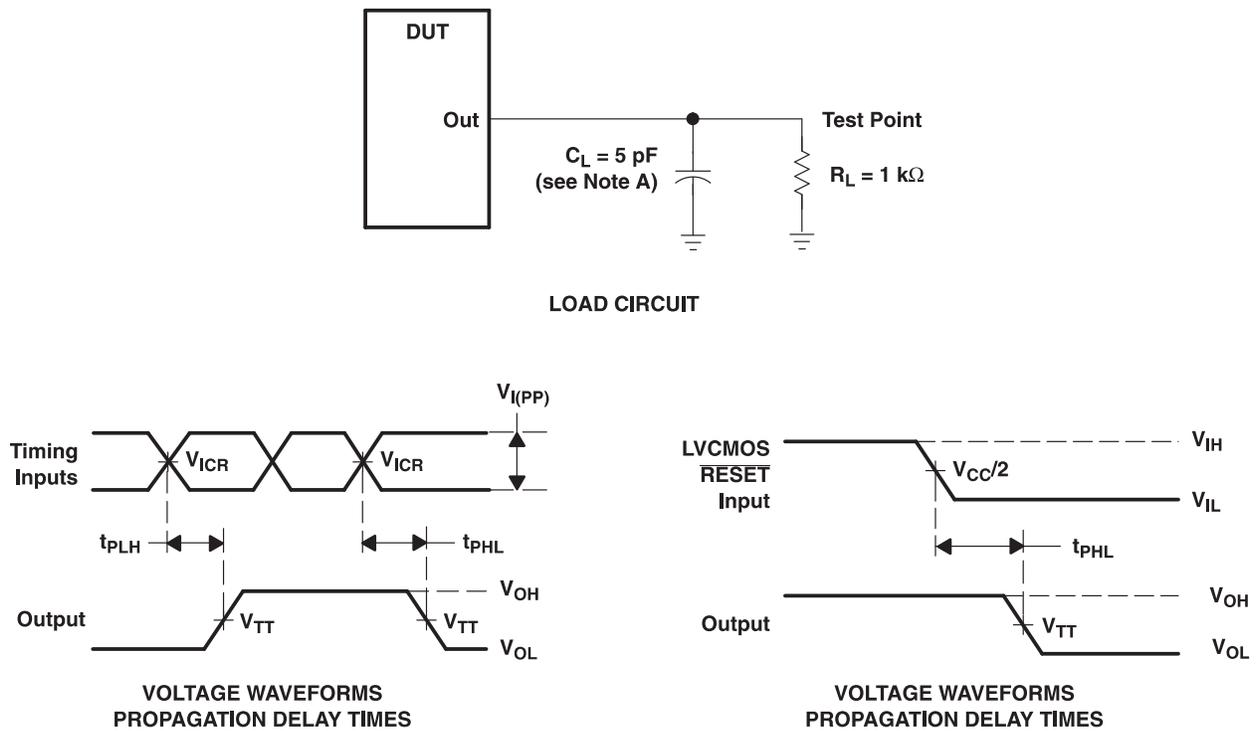
- NOTES: A. C_L includes probe and jig capacitance.
 B. All input pulses are supplied by generators having the following characteristics: $PRR \leq 10 \text{ MHz}$, $Z_O = 50 \Omega$, input slew rate = $1 \text{ V/ns} \pm 20\%$ (unless otherwise specified).

Figure 3. Data Output Slew-Rate Measurement Information



- NOTES: A. C_L includes probe and jig capacitance.
 B. All input pulses are supplied by generators having the following characteristics: $PRR \leq 10\text{ MHz}$, $Z_O = 50\ \Omega$, input slew rate = $1\text{ V/ns} \pm 20\%$ (unless otherwise noted).
 C. t_{PLH} and t_{PHL} are the same as t_{pd} .

Figure 4. Error Output Load Circuit and Voltage Waveforms



- NOTES:
- A. C_L includes probe and jig capacitance.
 - B. All input pulses are supplied by generators having the following characteristics: $PRR \leq 10$ MHz, $Z_O = 50 \Omega$, input slew rate = 1 V/ns $\pm 20\%$ (unless otherwise noted).
 - C. $V_{REF} = V_{TT} = V_{CC}/2$
 - D. $V_{IH} = V_{REF} + 250$ mV (ac voltage levels) for differential inputs. $V_{IH} = V_{CC}$ for LVC MOS input.
 - E. $V_{IL} = V_{REF} - 250$ mV (ac voltage levels) for differential inputs. $V_{IL} = GND$ for LVC MOS input.
 - F. $V_{I(PP)} = 600$ mV
 - G. t_{PLH} and t_{PHL} are the same as t_{pd} .

Figure 5. Partial-Parity-Out Load Circuit and Voltage Waveforms

APPLICATION INFORMATION

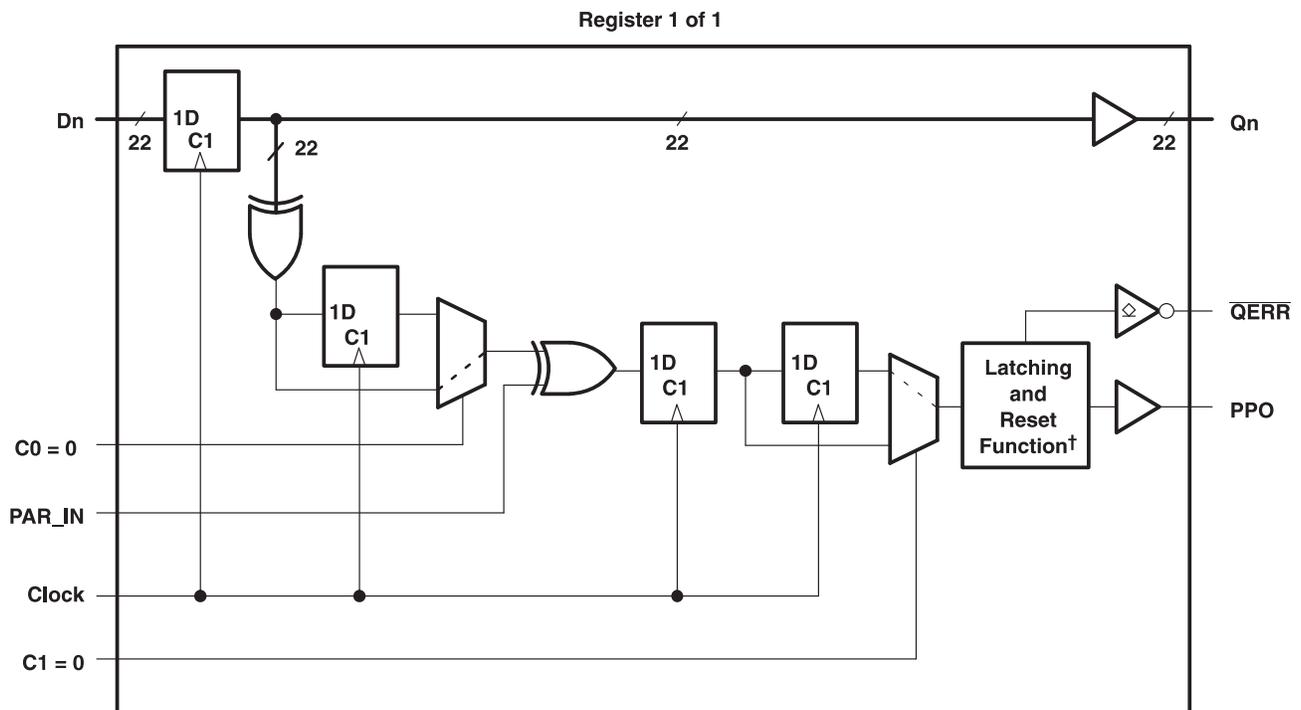
The typical values below are for standard raw cards. Test equipment used was the JEDEC register validation board using pattern 0x43, 0x4F, and 0x5A.

Table 1. Raw Card Values ⁽¹⁾⁽²⁾

RAW CARD	t_{pdmss}		OVERSHOOT
	MIN	MAX	
A/F	1.2 ns	1.6 ns	140 mV
B/G	1.3 ns	2.0 ns	430 mV
C/H	1.3 ns	2.0 ns	430 mV

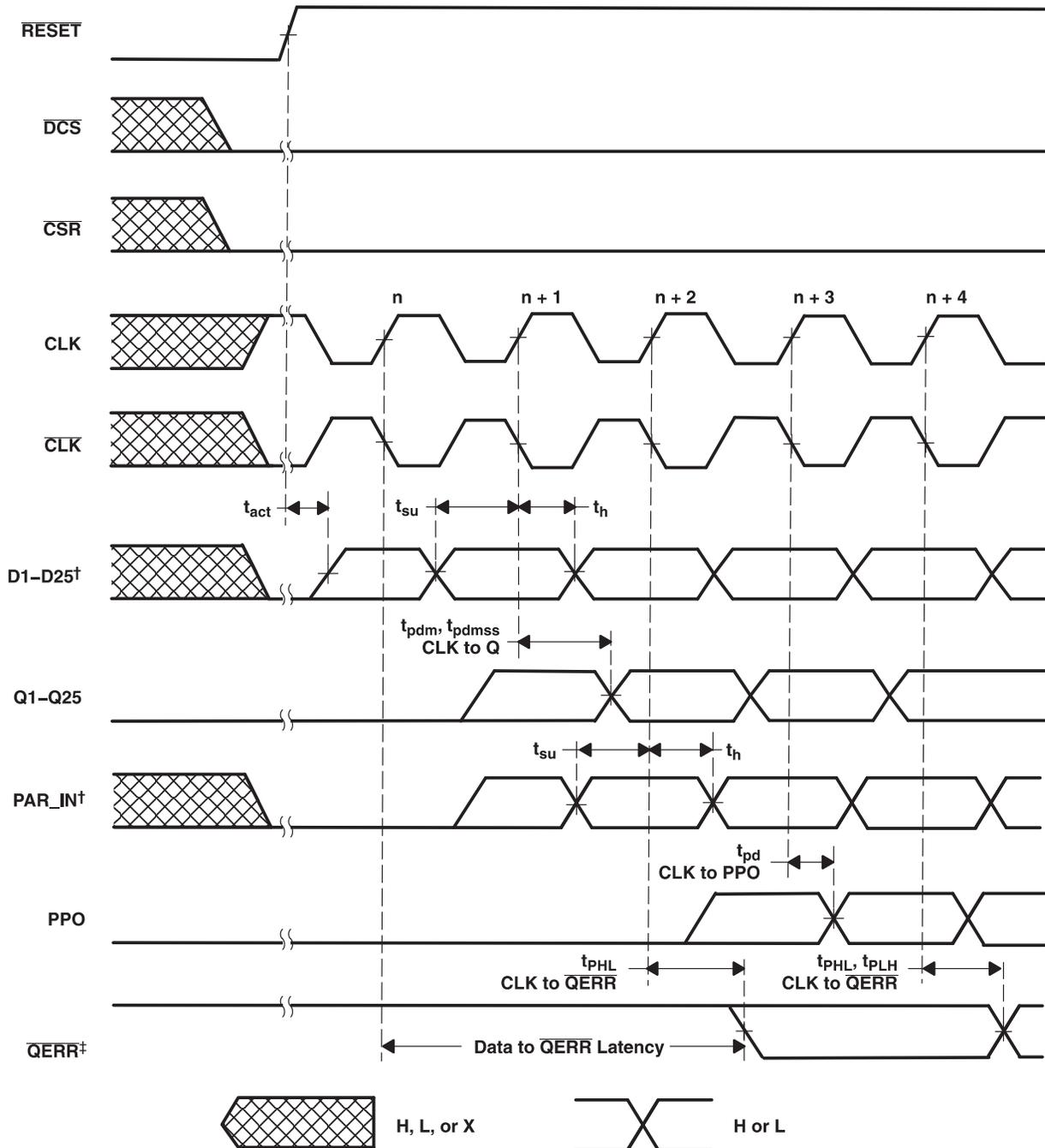
- (1) All values are valid under nominal conditions and minimum/maximum of typical signals on one typical DIMM.
- (2) Measurements include all jitter and ISI effects.

SN74SSTUB32866 Used as a Single Device in the 1:1 Register Configuration; C0 = 0, C1 = 0



† This function holds the error for two cycles. For details, see the parity logic diagram.

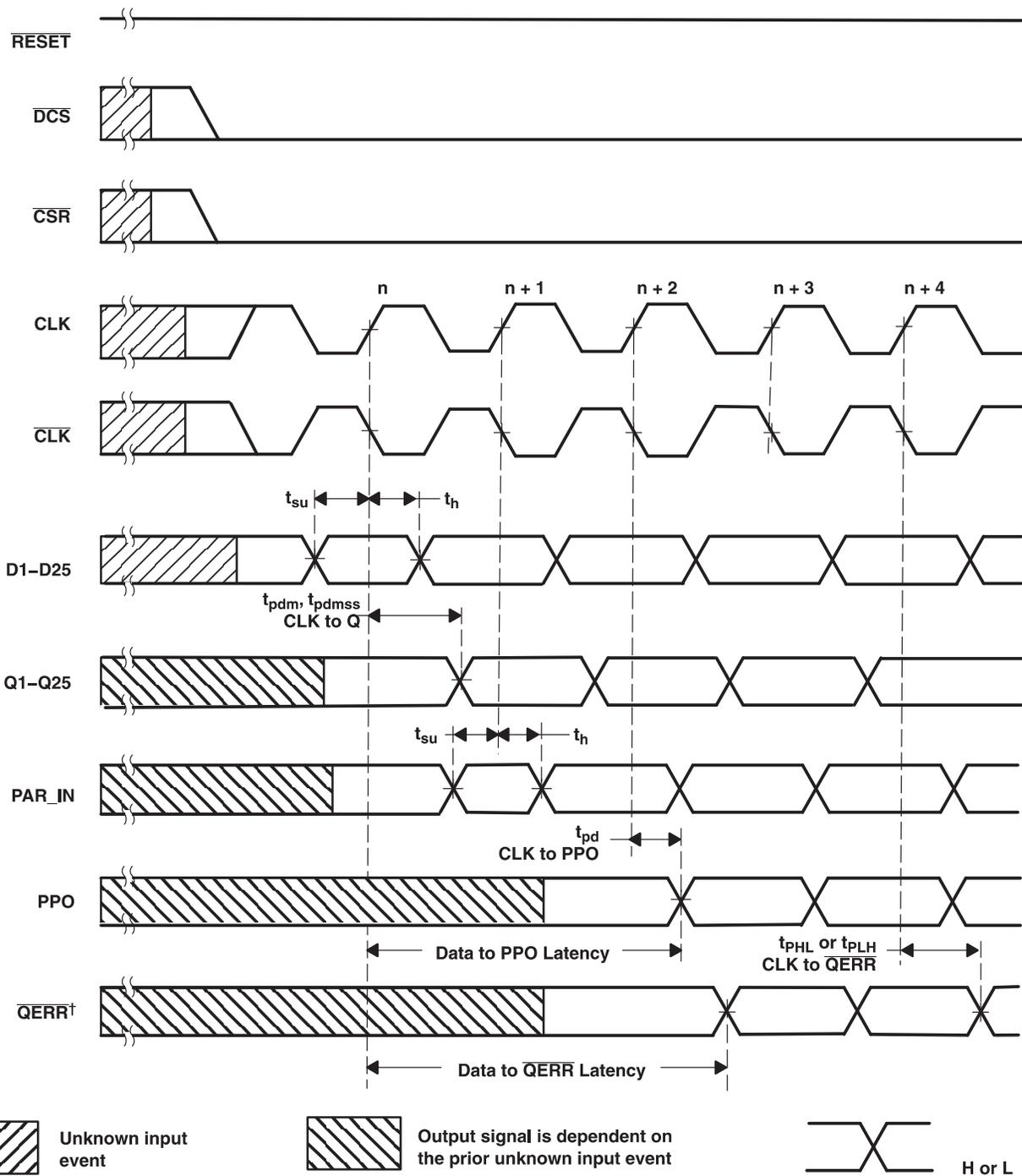
Timing Diagram for SN74SSTUB32866 Used as a Single Device; C0 = 0, C1 = 0 ($\overline{\text{RESET}}$ Switches From L to H)



† After $\overline{\text{RESET}}$ is switched from low to high, all data and PAR_IN input signals must be set and held low for a minimum time of t_{act} max, to avoid false error.

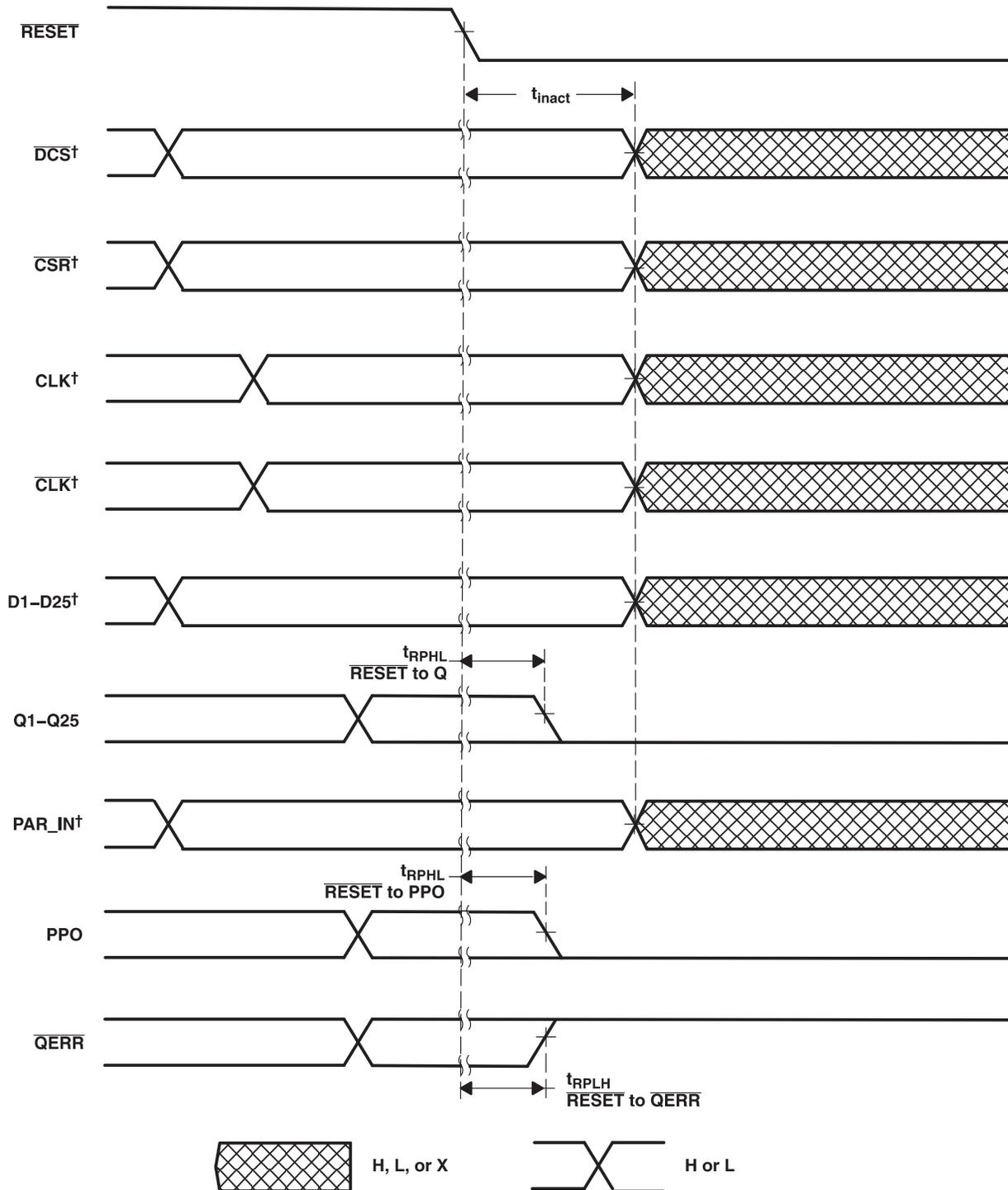
‡ If the data is clocked in on the n clock pulse, the $\overline{\text{QERR}}$ output signal will be generated on the n + 2 clock pulse, and it will be valid on the n + 3 clock pulse.

Timing Diagram for SN74SSTUB32866 Used as a Single Device; C0 = 0, C1 = 0 ($\overline{\text{RESET}} = \text{H}$)



† If the data is clocked in on the n clock pulse, the $\overline{\text{QERR}}$ output signal will be generated on the n + 2 clock pulse, and it will be valid on n + 3 clock pulse. If an error occurs and the QERR output is driven low, it stays latched low for a minimum of two clock cycles or until RESET is driven low.

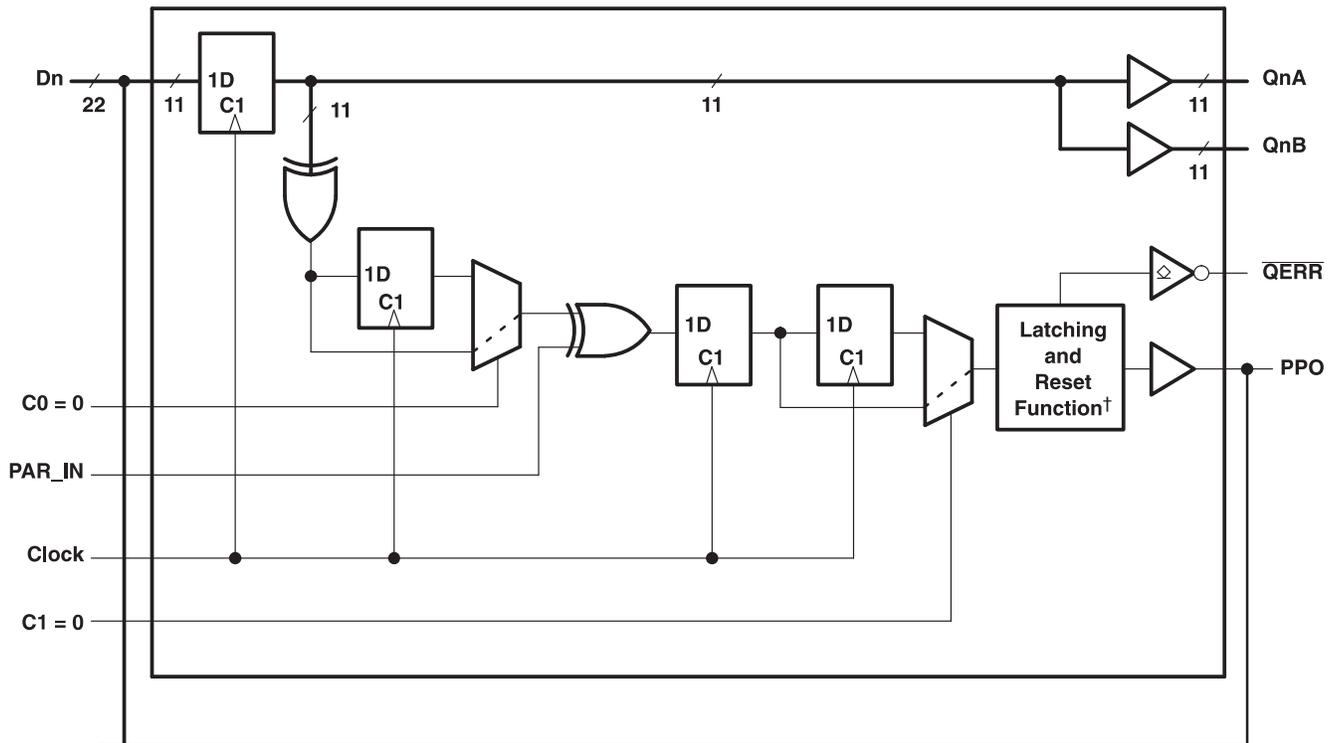
Timing Diagram for SN74SSTUB32866 Used as a Single Device; C0 = 0, C1 = 0 ($\overline{\text{RESET}}$ Switches From = H to L)



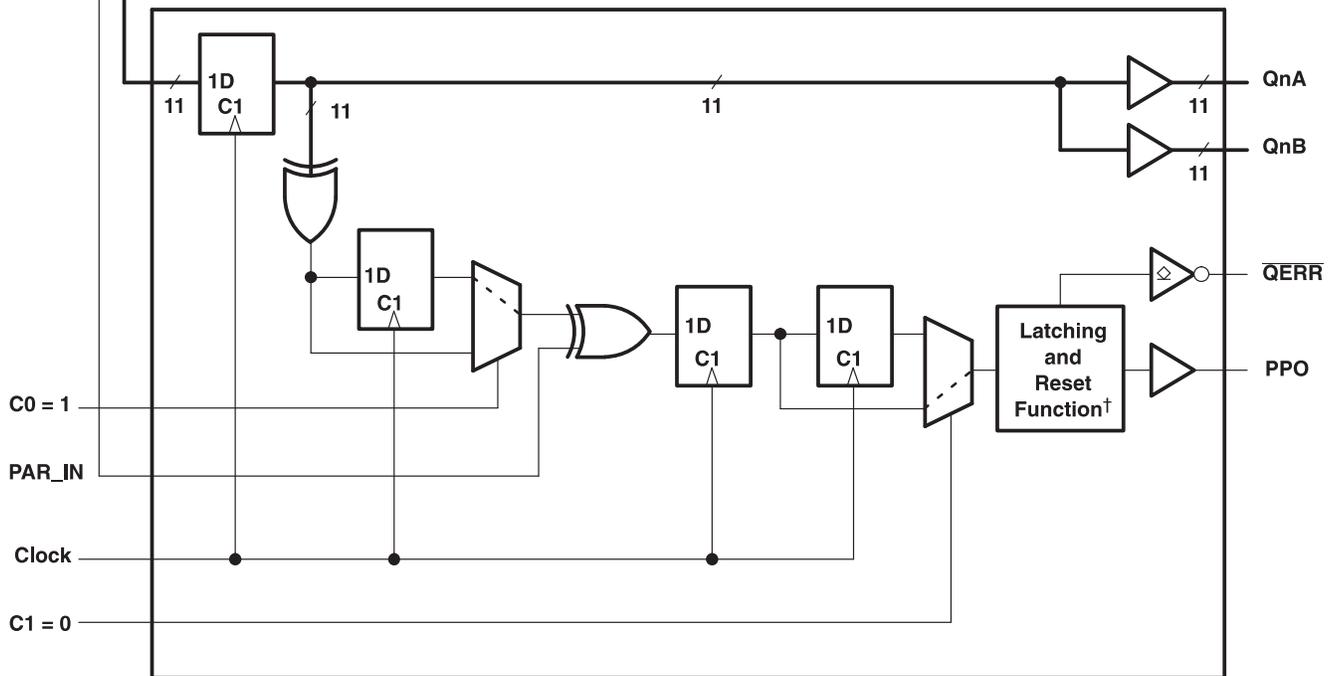
† After $\overline{\text{RESET}}$ is switched from high to low, all data and clock input signals must be held at valid logic levels (not floating) for a minimum time of $t_{\text{inact}} \text{ max.}$

SN74SSTUB32866 Used in Pair in the 1:2 Register Configuration

Register 1 of 2 (1:2 Register-A Configuration); C0 = 0, C1 = 1

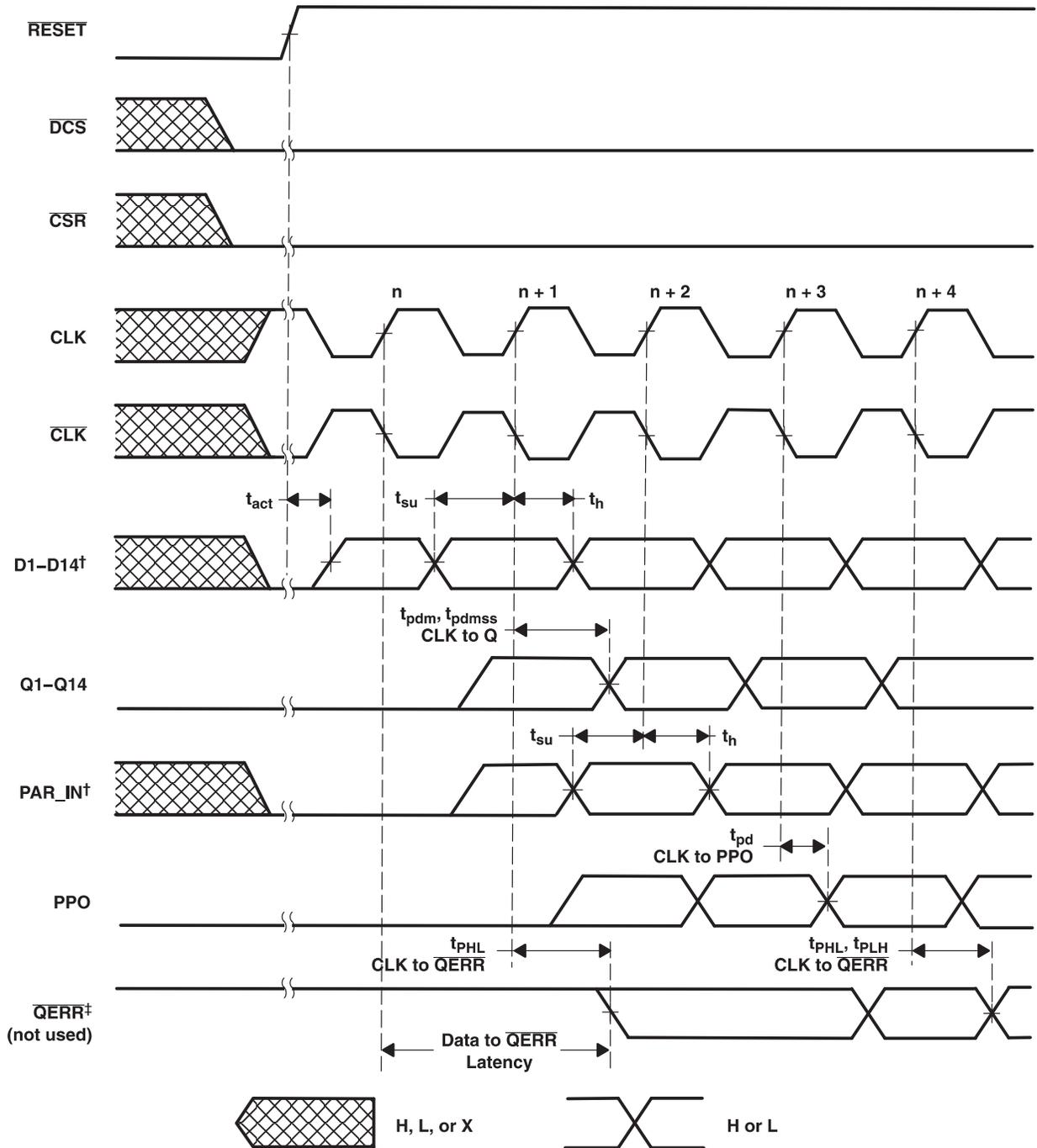


Register 2 of 2 (1:2 Register-B Configuration); C0 = 1, C1 = 1



† This function holds the error for two cycles. For details, see the parity logic diagram.

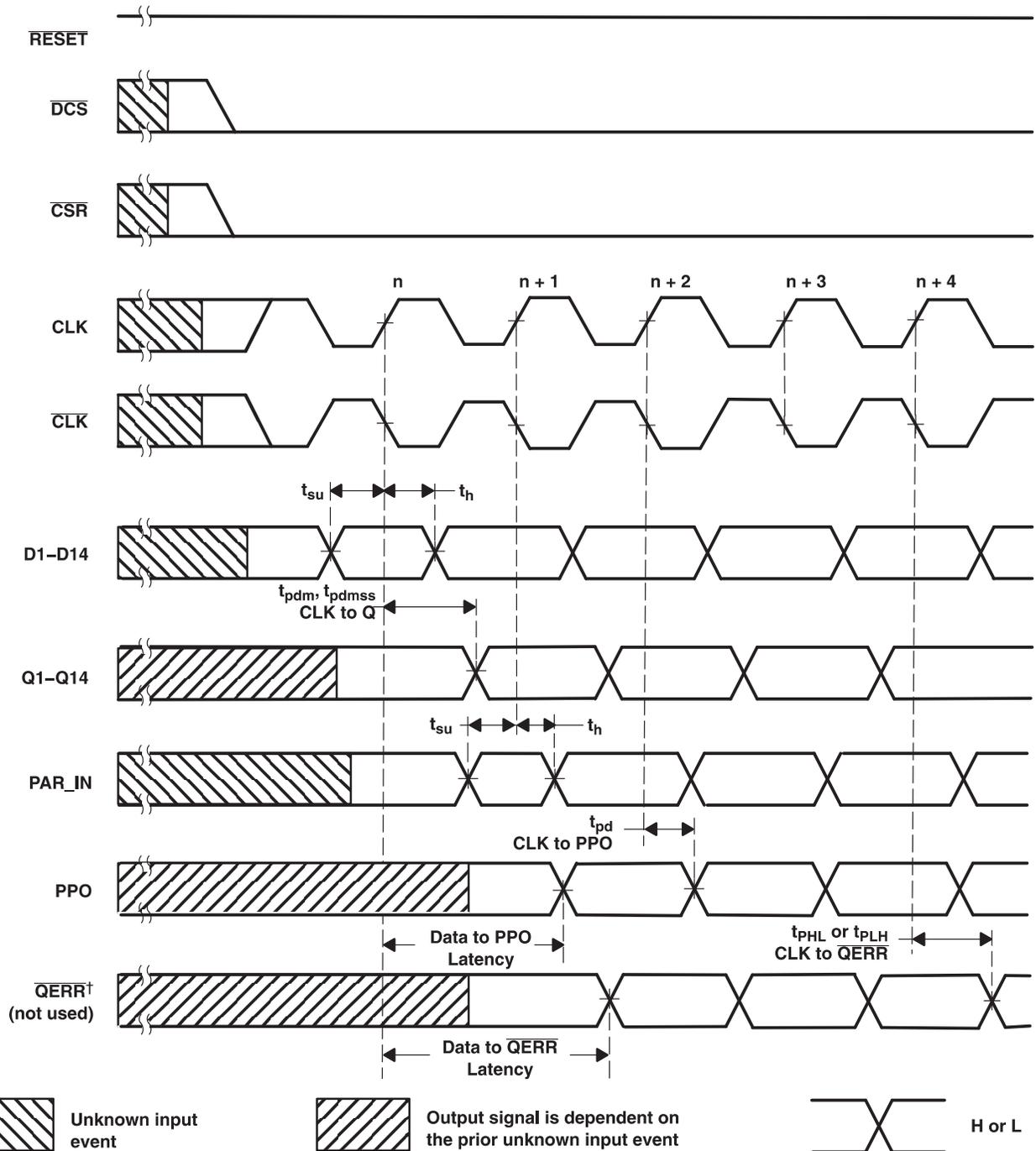
Timing Diagram for the First SN74SSTUB32866 (1:2 Register-A Configuration) Device Used in Pair; C0 = 0, C1 = 1 (RESET Switches From L to H)



† After $\overline{\text{RESET}}$ is switched from low to high, all data and PAR_IN input signals must be set and held low for a minimum time of t_{act} max, to avoid false error.

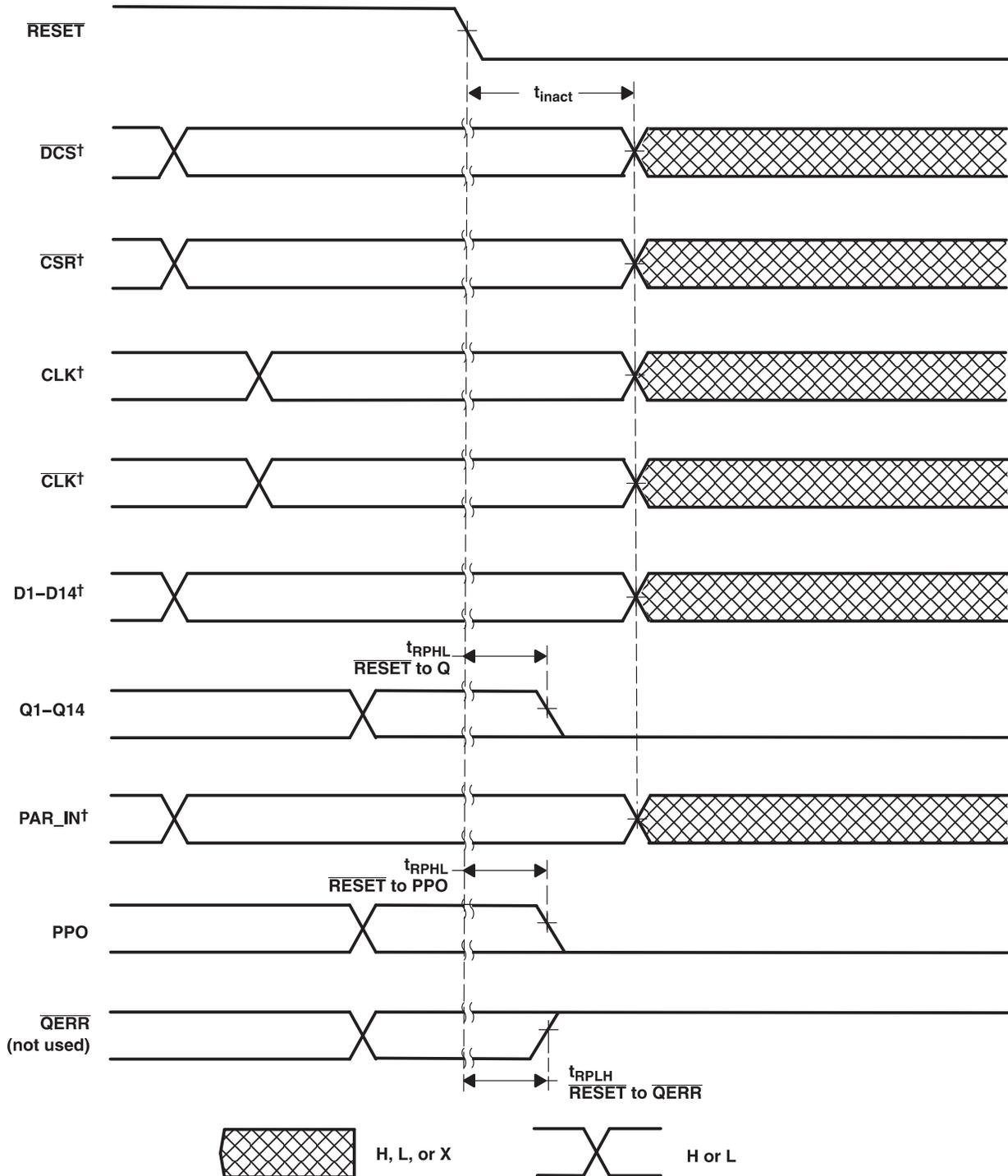
‡ If the data is clocked in on the n clock pulse, the $\overline{\text{QERR}}$ output signal will be generated on the n + 1 clock pulse, and it will be valid on the n + 2 clock pulse.

Timing Diagram for the First SN74SSTUB32866 (1:2 Register-A Configuration) Device Used in Pair; C0 = 0, C1 = 1 (RESET = H)



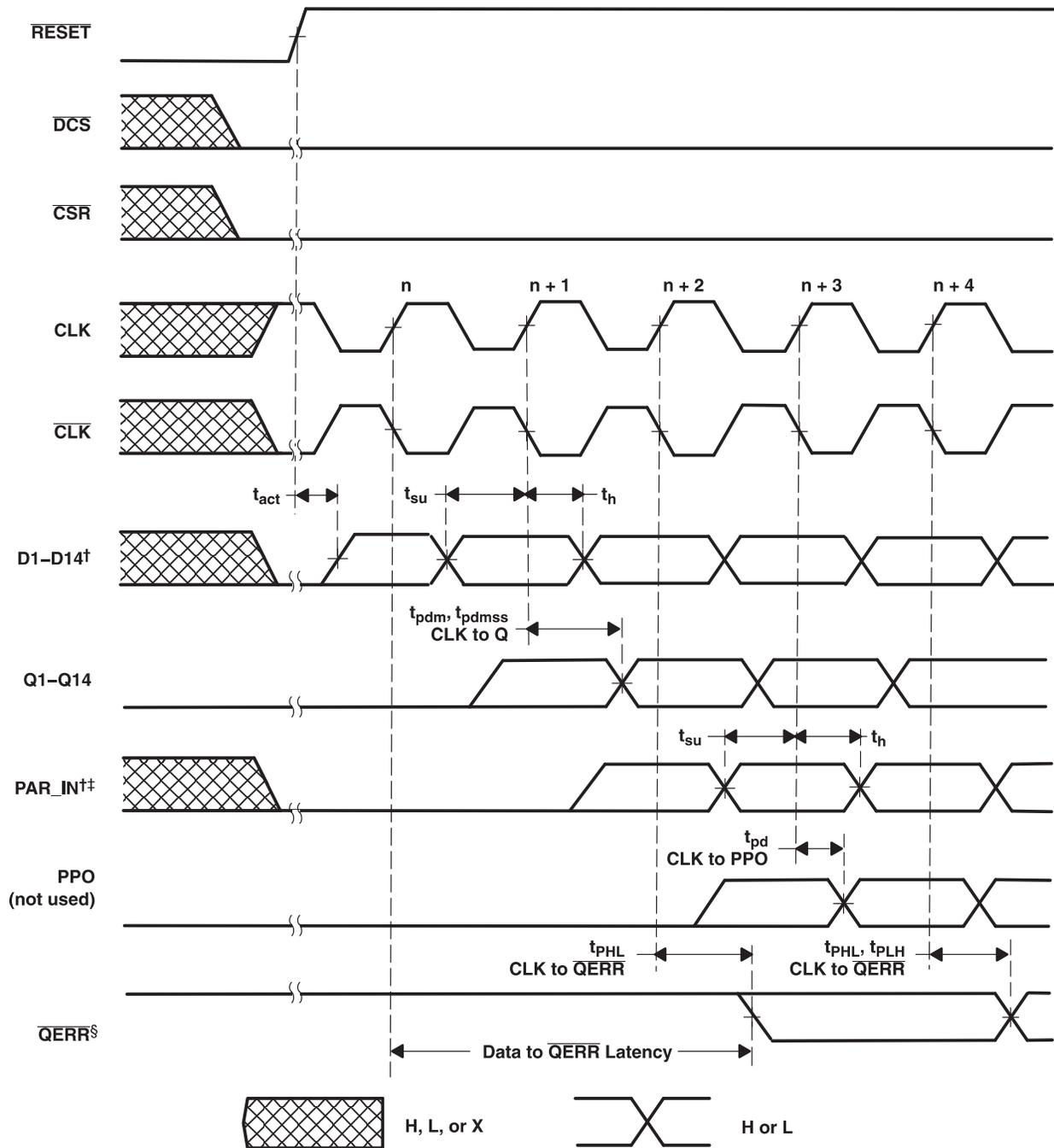
† If the data is clocked in on the n clock pulse, the \overline{QERR} output signal will be generated on the n + 1 clock pulse, and it will be valid on n + 2 clock pulse. If an error occurs and the \overline{QERR} output is driven low, it stays latched low for a minimum of two clock cycles or until RESET is driven low.

Timing Diagram for the First SN74SSTUB32866 (1:2 Register-A Configuration) Device Used in Pair; C0 = 0, C1 = 1 (RESET = Switches From H to L)



[†] After **RESET** is switched from high to low, all data and clock input signals must be held at valid logic levels (not floating) for a minimum time of t_{inact} max.

Timing Diagram for the Second SN74SSTUB32866 (1:2 Register-B Configuration) Device Used in Pair; C0 = 1, C1 = 1 (RESET = Switches From L to H)

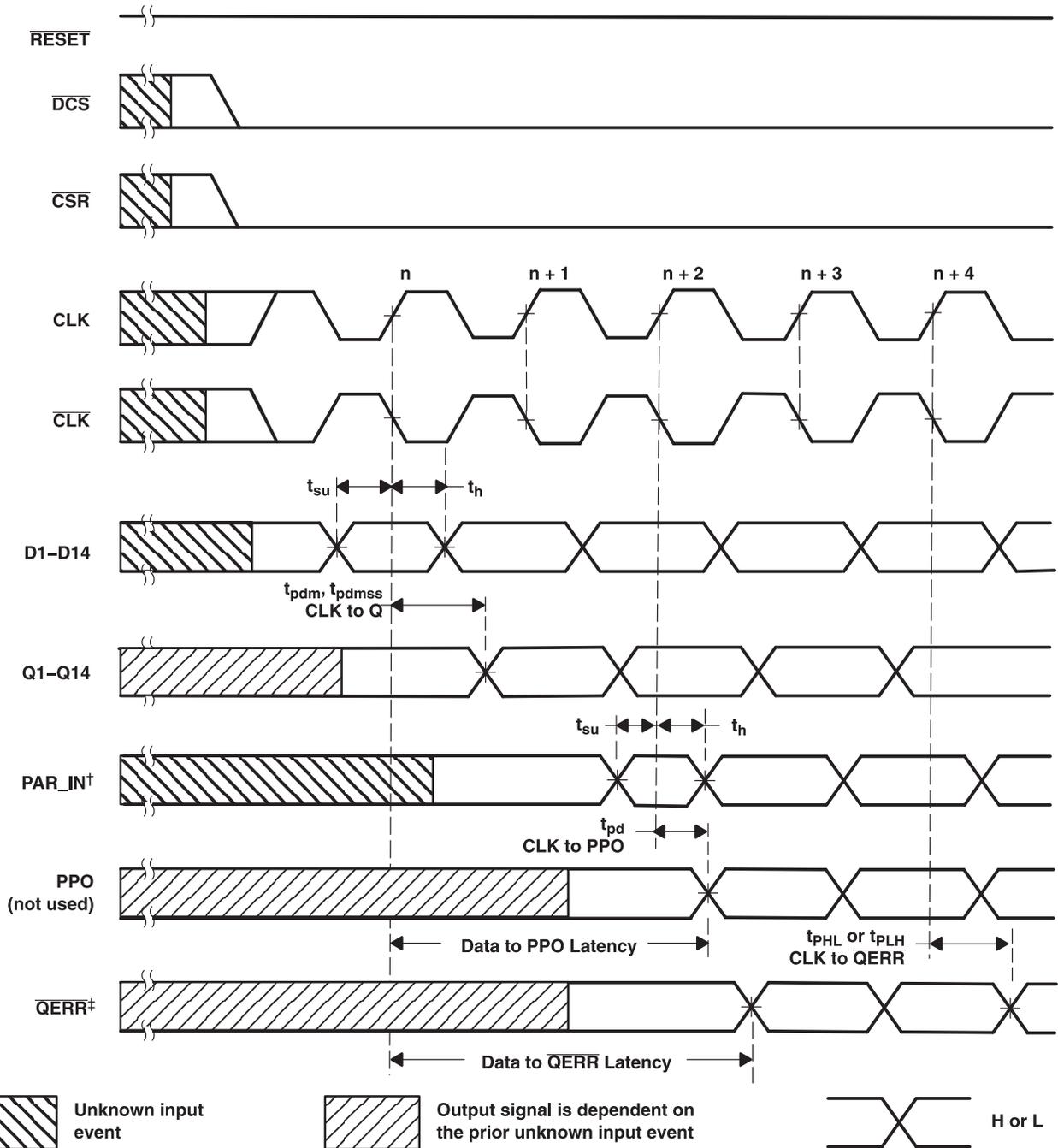


[†] After $\overline{\text{RESET}}$ is switched from low to high, all data and PAR_IN input signals must be set and held low for a minimum time of t_{act} max, to avoid false error.

[‡] PAR_IN is driven from PPO of the first SN74SSTUB32866 device.

[§] If the data is clocked in on the n clock pulse, the $\overline{\text{QERR}}$ output signal will be generated on the n + 2 clock pulse, and it will be valid on the n + 3 clock pulse.

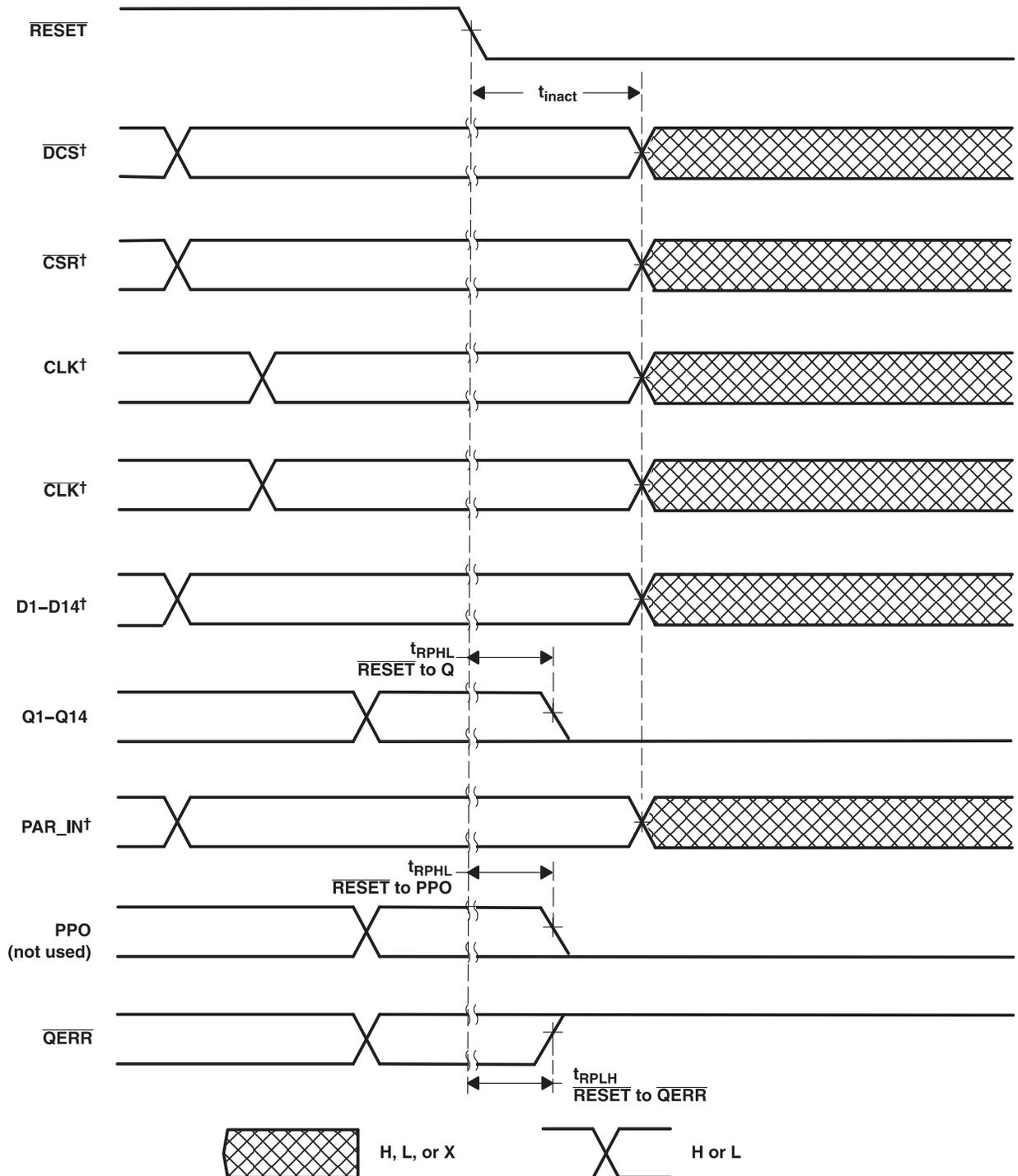
Timing Diagram for the Second SN74SSTUB32866 (1:2 Register-B Configuration) Device Used in Pair; C0 = 1, C1 = 1 (RESET = H)



[†] PAR_IN is driven from PPO of the first SN74SSTUB32866 device.

[‡] If the data is clocked in on the n clock pulse, the QERR output signal will be generated on the n + 2 clock pulse, and it will be valid on n + 3 clock pulse. If an error occurs and the QERR output is driven low, it stays latched low for a minimum of two clock cycles or until RESET is driven low.

Timing Diagram for the Second SN74SSTUB32866 (1:2 Register-B Configuration) Device Used in Pair; C0 = 1, C1 = 1 (RESET = Switches From H to L)



† After RESET is switched from high to low, all data and clock input signals must be held at valid logic levels (not floating) for a minimum time of t_{inact} max.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Interface	interface.ti.com	Digital Control	www.ti.com/digitalcontrol
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
Low Power Wireless	www.ti.com/lpw	Telephony	www.ti.com/telephony
		Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address: Texas Instruments
Post Office Box 655303 Dallas, Texas 75265